

Example 1.3: As an example, consider the following function:

$$f(x) = \begin{cases} 1, & \text{for } 0 < x < 1, \\ 0, & \text{otherwise.} \end{cases}$$

Clearly, since $f(x) \geq 0$ for $-\infty < x < \infty$ and $\int_{-\infty}^{\infty} f(x) dx = \int_0^1 f(x) dx = [x]_0^1 = 1$, the above function can be a probability density function.

In fact, it is called a **uniform distribution**.

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$$\begin{aligned} I^2 &= \left(\int_{-\infty}^{\infty} f(x) dx \right)^2 = \left(\int_{-\infty}^{\infty} f(x) dx \right) \left(\int_{-\infty}^{\infty} f(y) dy \right) \\ &= \left(\int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}x^2\right) dx \right) \left(\int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}y^2\right) dy \right) \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \exp\left(-\frac{1}{2}(x^2 + y^2)\right) dx dy \\ &= \frac{1}{2\pi} \int_0^{2\pi} \int_0^{\infty} \exp\left(-\frac{1}{2}r^2\right) r dr d\theta \\ &= \frac{1}{2\pi} \int_0^{2\pi} \int_0^{\infty} \exp(-s) ds d\theta = \frac{1}{2\pi} 2\pi [-\exp(-s)]_0^{\infty} = 1. \end{aligned}$$

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Proof:

Let $F(x)$ be the integration of $f(x)$, i.e.,

$$F(x) = \int_{-\infty}^x f(t) dt,$$

which implies that $F'(x) = f(x)$.

Differentiating $F(x) = F(\psi(y))$ with respect to y , we have:

$$f(x) \equiv \frac{dF(\psi(y))}{dy} = \frac{dF(x)}{dx} \frac{dx}{dy} = f(x)\psi'(y) = f(\psi(y))\psi'(y).$$

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Example 1.4: As another example, consider the following function:

$$f(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}x^2},$$

for $-\infty < x < \infty$.

Clearly, we have $f(x) \geq 0$ for all x .

We check whether $\int_{-\infty}^{\infty} f(x) dx = 1$.

First of all, we define I as $I = \int_{-\infty}^{\infty} f(x) dx$.

To show $I = 1$, we may prove $I^2 = 1$ because of $f(x) > 0$ for all x , which is shown as follows:

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< Review > Integration by Substitution (置換積分):

Univariate (1 変数) Case: For a function of x , $f(x)$, we perform integration by substitution, using $x = \psi(y)$.

Then, it is easy to obtain the following formula:

$$\int f(x) dx = \int \psi'(y) f(\psi(y)) dy,$$

which formula is called the **integration by substitution**.

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Bivariate (2 変数) Case: For $f(x, y)$, define $x = \psi_1(u, v)$ and $y = \psi_2(u, v)$.

$$\iint f(x, y) dx dy = \iint J f(\psi_1(u, v), \psi_2(u, v)) du dv,$$

where J is called the **Jacobian (ヤコビアン)**, which represents the following determinant (行列式):

$$J = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u}.$$

< End of Review >

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< Go back to the Integration >

In the fifth equality, integration by substitution (置換積分) is used.

The polar coordinate transformation (極座標変換) is used as $x = r \cos \theta$ and $y = r \sin \theta$.

Note that $0 \leq r < +\infty$ and $0 \leq \theta < 2\pi$.

The Jacobian is given by:

$$J = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r.$$

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In the inner integration of the sixth equality, again, integration by substitution is utilized, where transformation is $s = \frac{1}{2}r^2$.

Thus, we obtain the result $I^2 = 1$ and accordingly we have $I = 1$ because of $f(x) \geq 0$.

Therefore, $f(x) = e^{-\frac{1}{2}x^2} / \sqrt{2\pi}$ is also taken as a probability density function.

Actually, this density function is called the **standard normal probability density function** (標準正規分布).

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Distribution Function: The **distribution function** (分布関数) or the **cumulative distribution function** (累積分布関数), denoted by $F(x)$, is defined as:

$$P(X \leq x) = F(x),$$

which represents the probability less than x .

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The properties of the distribution function $F(x)$ are given by:

$$F(x_1) \leq F(x_2), \quad \text{for } x_1 < x_2, \quad \text{---> nondecreasing function}$$

$$P(a < X \leq b) = F(b) - F(a), \quad \text{for } a < b,$$

$$F(-\infty) = 0, \quad F(+\infty) = 1.$$

The difference between the discrete and continuous random variables is given by:

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1. Discrete random variable (Figure 1):

$$\bullet F(x) = \sum_{i=1}^r f(x_i) = \sum_{i=1}^r p_i,$$

where r denotes the integer which satisfies $x_r \leq x < x_{r+1}$.

$$\bullet F(x_i) - F(x_i - \epsilon) = f(x_i) = p_i,$$

where ϵ is a small positive number less than $x_i - x_{i-1}$.

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2. Continuous random variable (Figure 2):

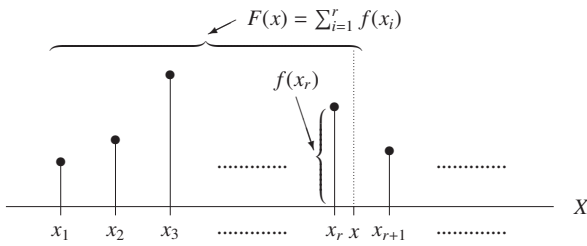
$$\bullet F(x) = \int_{-\infty}^x f(t) dt,$$

$$\bullet F'(x) = f(x).$$

$f(x)$ and $F(x)$ are displayed in Figure 1 for a discrete random variable and Figure 2 for a continuous random variable.

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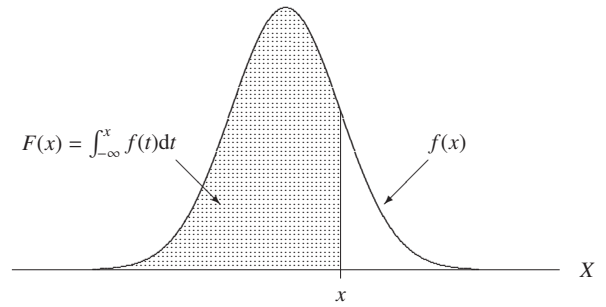
Figure 1: Probability Function $f(x)$ and Distribution Function $F(x)$ — Discrete Case



Note that r is the integer which satisfies $x_r \leq x < x_{r+1}$.

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Figure 2: Density Function $f(x)$ and Distribution Function $F(x)$ — Continuous Case



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2.2 Multivariate Random Variable (多変量確率変数) and Distribution

We consider two random variables X and Y in this section. It is easy to extend to more than two random variables.

Discrete Random Variables: Suppose that discrete random variables X and Y take x_1, x_2, \dots and y_1, y_2, \dots , respectively. The probability which event $\{\omega; X(\omega) = x_i \text{ and } Y(\omega) = y_j\}$ occurs is given by:

$$P(X = x_i, Y = y_j) = f_{xy}(x_i, y_j),$$

where $f_{xy}(x_i, y_j)$ represents the **joint probability function** (結合確率関数) of X and Y . In order for $f_{xy}(x_i, y_j)$ to be a joint probability function, $f_{xy}(x_i, y_j)$ has to satisfy the following properties:

$$f_{xy}(x_i, y_j) \geq 0, \quad i, j = 1, 2, \dots$$

$$\sum_i \sum_j f_{xy}(x_i, y_j) = 1.$$

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Define $f_x(x_i)$ and $f_y(y_j)$ as:

$$f_x(x_i) = \sum_j f_{xy}(x_i, y_j), \quad i = 1, 2, \dots,$$

$$f_y(y_j) = \sum_i f_{xy}(x_i, y_j), \quad j = 1, 2, \dots.$$

Then, $f_x(x_i)$ and $f_y(y_j)$ are called the **marginal probability functions** (周辺確率関数) of X and Y .

$f_x(x_i)$ and $f_y(y_j)$ also have the properties of the probability functions, i.e.,

$f_x(x_i) \geq 0$ and $\sum_i f_x(x_i) = 1$, and $f_y(y_j) \geq 0$ and $\sum_j f_y(y_j) = 1$.

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Continuous Random Variables: Consider two continuous random variables X and Y . For a domain D , the probability which event $\{\omega; (X(\omega), Y(\omega)) \in D\}$ occurs is given by:

$$P((X, Y) \in D) = \iint_D f_{xy}(x, y) dx dy,$$

where $f_{xy}(x, y)$ is called the **joint probability density function** (結合確率密度関数) of X and Y or the **joint density function** of X and Y .

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$f_{xy}(x, y)$ has to satisfy the following properties:

$$f_{xy}(x, y) \geq 0, \\ \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{xy}(x, y) dx dy = 1.$$

Define $f_x(x)$ and $f_y(y)$ as:

$$f_x(x) = \int_{-\infty}^{\infty} f_{xy}(x, y) dy, \quad \text{for all } x \text{ and } y, \\ f_y(y) = \int_{-\infty}^{\infty} f_{xy}(x, y) dx,$$

where $f_x(x)$ and $f_y(y)$ are called the **marginal probability**

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density functions (周辺確率密度関数) of X and Y or the **marginal density functions** (周辺密度関数) of X and Y .

For example, consider the event $\{\omega; a < X(\omega) < b, c < Y(\omega) < d\}$, which is a specific case of the domain D . Then, the probability that we have the event $\{\omega; a < X(\omega) < b, c < Y(\omega) < d\}$ is written as:

$$P(a < X < b, c < Y < d) = \int_a^b \int_c^d f_{xy}(x, y) dx dy.$$

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The mixture of discrete and continuous RVs is also possible. For example, let X be a discrete RV and Y be a continuous RV. X takes x_1, x_2, \dots . The probability which both X takes x_i and Y takes real numbers within the interval I is given by:

$$P(X = x_i, Y \in I) = \int_I f_{xy}(x_i, y) dy.$$

Then, we have the following properties:

$$f_{xy}(x_i, y) \geq 0, \quad \text{for all } y \text{ and } i = 1, 2, \dots, \\ \sum_i \int_{-\infty}^{\infty} f_{xy}(x_i, y) dy = 1.$$

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The marginal probability function of X is given by:

$$f_x(x_i) = \int_{-\infty}^{\infty} f_{xy}(x_i, y) dy,$$

for $i = 1, 2, \dots$. The marginal probability density function of Y is:

$$f_y(y) = \sum_i f_{xy}(x_i, y).$$

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2.3 Conditional Distribution

Discrete Random Variable: The **conditional probability function** (条件付確率関数) of X given $Y = y_j$ is represented as:

$$P(X = x_i | Y = y_j) = f_{x|y}(x_i | y_j) = \frac{f_{xy}(x_i, y_j)}{f_y(y_j)} = \frac{f_{xy}(x_i, y_j)}{\sum_i f_{xy}(x_i, y_j)}.$$

The second equality indicates the definition of the conditional probability.

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The features of the conditional probability function $f_{x|y}(x_i | y_j)$ are:

$$f_{x|y}(x_i | y_j) \geq 0, \quad i = 1, 2, \dots, \\ \sum_i f_{x|y}(x_i | y_j) = 1, \quad \text{for any } j.$$

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Continuous Random Variable: The **conditional probability density function** (条件付確率密度関数) of X given $Y = y$ (or the **conditional density function** (条件付密度関数) of X given $Y = y$) is:

$$f_{x|y}(x|y) = \frac{f_{xy}(x, y)}{f_y(y)} = \frac{f_{xy}(x, y)}{\int_{-\infty}^{\infty} f_{xy}(x, y) dx}$$

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The properties of the conditional probability density function $f_{x|y}(x|y)$ are given by:

$$f_{x|y}(x|y) \geq 0, \\ \int_{-\infty}^{\infty} f_{x|y}(x|y) dx = 1, \quad \text{for any } Y = y.$$

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Independence of Random Variables: For discrete random variables X and Y , we say that X is **independent** (独立) (or **stochastically independent** (確率的に独立)) of Y if and only if $f_{xy}(x_i, y_j) = f_x(x_i)f_y(y_j)$.

Similarly, for continuous random variables X and Y , we say that X is independent of Y if and only if $f_{xy}(x, y) = f_x(x)f_y(y)$.

When X and Y are stochastically independent, $g(X)$ and $h(Y)$ are also stochastically independent, where $g(X)$ and $h(Y)$ are functions of X and Y .

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