Some Formulas of Mean and Variance: We consider two

random variables X and Y.

1. **Theorem:** E(X + Y) = E(X) + E(Y).

Proof:

For discrete random variables *X* and *Y*, it is given by:

$$E(X + Y) = \sum_{i} \sum_{j} (x_{i} + y_{j}) f_{xy}(x_{i}, y_{j})$$

= $\sum_{i} \sum_{j} x_{i} f_{xy}(x_{i}, y_{j}) + \sum_{i} \sum_{j} y_{j} f_{xy}(x_{i}, y_{j})$
= $E(X) + E(Y).$
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For continuous random variables *X* and *Y*, we can show:

$$E(X + Y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x + y) f_{xy}(x, y) dx dy$$

=
$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x f_{xy}(x, y) dx dy$$

+
$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} y f_{xy}(x, y) dx dy$$

=
$$E(X) + E(Y).$$

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2. **Theorem:** E(XY) = E(X)E(Y), when X is independent of Y.

Proof:

For discrete random variables X and Y,

$$E(XY) = \sum_{i} \sum_{j} x_i y_j f_{xy}(x_i, y_j) = \sum_{i} \sum_{j} x_i y_j f_x(x_i) f_y(y_j)$$
$$= \left(\sum_{i} x_i f_x(x_i)\right) \left(\sum_{j} y_j f_y(y_j)\right) = E(X)E(Y).$$

If X is independent of Y, the second equality holds, i.e., $f_{xy}(x_i, y_j) = f_x(x_i)f_y(y_j)$.

For continuous random variables X and Y,

$$E(XY) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy f_{xy}(x, y) dx dy$$

=
$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy f_x(x) f_y(y) dx dy$$

=
$$\left(\int_{-\infty}^{\infty} x f_x(x) dx \right) \left(\int_{-\infty}^{\infty} y f_y(y) dy \right) = E(X)E(Y).$$

When *X* is independent of *Y*, we have $f_{xy}(x, y) = f_x(x)f_y(y)$ in the second equality.



3. **Theorem:** Cov(X, Y) = E(XY) - E(X)E(Y).

Proof:

For both discrete and continuous random variables, we can rewrite as follows:

$$Cov(X, Y) = E((X - \mu_x)(Y - \mu_y))$$
$$= E(XY - \mu_x Y - \mu_y X + \mu_x \mu_y)$$
$$= E(XY) - E(\mu_x Y) - E(\mu_y X) + \mu_x \mu_y$$
$$= E(XY) - \mu_x E(Y) - \mu_y E(X) + \mu_x \mu_y$$

 $= E(XY) - \mu_x \mu_y - \mu_y \mu_x + \mu_x \mu_y$ $= E(XY) - \mu_x \mu_y$ = E(XY) - E(X)E(Y).

In the fourth equality, the theorem in Section 3.1 is used, i.e., $E(\mu_x Y) = \mu_x E(Y)$ and $E(\mu_y X) = \mu_y E(X)$. 4. **Theorem:** Cov(X, Y) = 0, when X is independent of *Y*.

Proof:

From the above two theorems, we have E(XY) = E(X)E(Y)when *X* is independent of *Y* and Cov(X, Y) = E(XY) - E(X)E(Y).

Therefore, Cov(X, Y) = 0 is obtained when X is independent of Y.

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5. Definition: The correlation coefficient (相関係数)

between X and Y, denoted by ρ_{xy} , is defined as:

$$\rho_{xy} = \frac{\operatorname{Cov}(X, Y)}{\sqrt{\operatorname{V}(X)}\sqrt{\operatorname{V}(Y)}} = \frac{\operatorname{Cov}(X, Y)}{\sigma_x \sigma_y}$$

 $\rho_{xy} > 0 \implies \text{positive correlation between } X \text{ and } Y$ $\rho_{xy} \longrightarrow 1 \implies \text{strong positive correlation}$ $\rho_{xy} < 0 \implies \text{negative correlation between } X \text{ and } Y$ $\rho_{xy} \longrightarrow -1 \implies \text{strong negative correlation}$

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6. **Theorem:** $\rho_{xy} = 0$, when *X* is independent of *Y*.

Proof:

When *X* is independent of *Y*, we have Cov(X, Y) = 0. We obtain the result $\rho_{xy} = \frac{Cov(X, Y)}{\sqrt{V(X)}\sqrt{V(Y)}} = 0$. However, note that $\rho_{xy} = 0$ does not mean the independence between *X* and *Y*. 7. **Theorem:** $V(X \pm Y) = V(X) \pm 2Cov(X, Y) + V(Y).$

Proof:

For both discrete and continuous random variables, $V(X \pm Y)$ is rewritten as follows:

$$V(X \pm Y) = E(((X \pm Y) - E(X \pm Y))^2)$$

= $E(((X - \mu_x) \pm (Y - \mu_y))^2)$
= $E((X - \mu_x)^2 \pm 2(X - \mu_x)(Y - \mu_y) + (Y - \mu_y)^2)$

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8. **Theorem:** $-1 \le \rho_{xy} \le 1$.

Proof:

Consider the following function of t: f(t) = V(Xt - Y), which is always greater than or equal to zero because of the definition of variance. Therefore, for all t, we have $f(t) \ge 0$. f(t) is rewritten as follows:

$$= E((X - \mu_x)^2) \pm 2E((X - \mu_x)(Y - \mu_y)) +E((Y - \mu_y)^2) = V(X) \pm 2Cov(X, Y) + V(Y).$$

$$f(t) = V(Xt - Y) = V(Xt) - 2Cov(Xt, Y) + V(Y)$$
$$= t^2 V(X) - 2tCov(X, Y) + V(Y)$$
$$= V(X) \left(t - \frac{Cov(X, Y)}{V(X)}\right)^2 + V(Y) - \frac{(Cov(X, Y))^2}{V(X)}$$

In order to have $f(t) \ge 0$ for all *t*, we need the following condition:

$$V(Y) - \frac{(Cov(X, Y))^2}{V(X)} \ge 0,$$

because the first term in the last equality is nonnega-

tive, which implies:

$$\frac{(\operatorname{Cov}(X,Y))^2}{\operatorname{V}(X)\operatorname{V}(Y)} \le 1.$$

Therefore, we have:

$$-1 \le \frac{\operatorname{Cov}(X, Y)}{\sqrt{\operatorname{V}(X)}\sqrt{\operatorname{V}(Y)}} \le 1$$

From the definition of correlation coefficient, i.e., $\rho_{xy} = \frac{\text{Cov}(X, Y)}{\sqrt{V(X)}\sqrt{V(Y)}}$, we obtain the result: $-1 \le \rho_{xy} \le 1$.

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10. **Theorem:** For *n* random variables X_1, X_2, \dots, X_n ,

$$E(\sum_{i} a_{i}X_{i}) = \sum_{i} a_{i}\mu_{i},$$
$$V(\sum_{i} a_{i}X_{i}) = \sum_{i} \sum_{j} a_{i}a_{j}Cov(X_{i}, X_{j}),$$

where $E(X_i) = \mu_i$ and a_i is a constant value. Especially, when X_1, X_2, \dots, X_n are mutually independent, we have the following:

$$\mathbf{V}(\sum_{i} a_{i}X_{i}) = \sum_{i} a_{i}^{2}\mathbf{V}(X_{i}).$$

For variance of $\sum_i a_i X_i$, we can rewrite as follows:

$$V(\sum_{i} a_{i}X_{i}) = E\left(\sum_{i} a_{i}(X_{i} - \mu_{i})\right)^{2}$$

= $E\left(\sum_{i} a_{i}(X_{i} - \mu_{i})\right)\left(\sum_{j} a_{j}(X_{j} - \mu_{j})\right)$
= $E\left(\sum_{i} \sum_{j} a_{i}a_{j}(X_{i} - \mu_{i})(X_{j} - \mu_{j})\right)$
= $\sum_{i} \sum_{j} a_{i}a_{j}E\left((X_{i} - \mu_{i})(X_{j} - \mu_{j})\right)$
= $\sum_{i} \sum_{j} a_{i}a_{j}Cov(X_{i}, X_{j}).$

When X_1, X_2, \dots, X_n are mutually independent, we

9. **Theorem:** $V(X \pm Y) = V(X) + V(Y)$, when X is independent of Y.

Proof:

From the theorem above, $V(X \pm Y) = V(X) \pm 2Cov(X, Y) + V(Y)$ generally holds. When random variables *X* and *Y* are independent, we have Cov(X, Y) = 0. Therefore, V(X + Y) = V(X) + V(Y) holds, when *X* is independent of *Y*.

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Proof:

For mean of $\sum_i a_i X_i$, the following representation is obtained.

$$\mathrm{E}(\sum_{i} a_{i}X_{i}) = \sum_{i} \mathrm{E}(a_{i}X_{i}) = \sum_{i} a_{i}\mathrm{E}(X_{i}) = \sum_{i} a_{i}\mu_{i}.$$

The first and second equalities come from the previous theorems on mean.

obtain $Cov(X_i, X_j) = 0$ for all $i \neq j$ from the previous theorem. Therefore, we obtain:

$$\mathbf{V}(\sum_{i} a_{i} X_{i}) = \sum_{i} a_{i}^{2} \mathbf{V}(X_{i}).$$

Note that $\operatorname{Cov}(X_i, X_i) = \operatorname{E}((X_i - \mu)^2) = \operatorname{V}(X_i)$.

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11. Theorem: *n* random variables X₁, X₂, ..., X_n are mutually independently and identically distributed with mean μ and variance σ². That is, for all *i* = 1, 2, ..., *n*, E(X_i) = μ and V(X_i) = σ² are assumed. Consider arithmetic average X̄ = (1/n) Σ_{i=1}ⁿ X_i. Then, mean and variance of X̄ are given by:

$$E(\overline{X}) = \mu, \qquad V(\overline{X}) = \frac{\sigma^2}{n}$$

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The variance of \overline{X} is computed as follows:

$$V(\overline{X}) = V(\frac{1}{n}\sum_{i=1}^{n}X_i) = \frac{1}{n^2}V(\sum_{i=1}^{n}X_i) = \frac{1}{n^2}\sum_{i=1}^{n}V(X_i)$$
$$= \frac{1}{n^2}\sum_{i=1}^{n}\sigma^2 = \frac{1}{n^2}n\sigma^2 = \frac{\sigma^2}{n}.$$

We use $V(aX) = a^2V(X)$ in the second equality and V(X + Y) = V(X) + V(Y) for *X* independent of *Y* in the third equality, where *X* and *Y* denote random variables and *a* is a constant value.



4 Transformation of Variables (変数変換)

Transformation of variables is used in the case of continuous random variables. Based on a distribution of a random variable, a distribution of the transformed random variable is derived. In other words, when a distribution of X is known, we can find a distribution of Y using the transformation of variables, where Y is a function of X.

4.1 Univariate Case

Distribution of $Y = \psi^{-1}(X)$: Let $f_x(x)$ be the probability density function of continuous random variable X and $X = \psi(Y)$ be a one-to-one $(- \not \neg \neg -)$ transformation. Then, the probability density function of Y, i.e., $f_y(y)$, is given by:

$$f_{y}(y) = |\psi'(y)| f_{x}(\psi(y)).$$

We can derive the above transformation of variables from *X* to *Y* as follows. Let $f_x(x)$ and $F_x(x)$ be the probability den-

Proof:

$$= \frac{1}{n} \sum_{i=1}^{n} \mu = \frac{1}{n} n \mu = \mu.$$

The mathematical expectation of \overline{X} is given by:

E(aX) = aE(X) in the second equality and E(X + Y) = E(X) + E(Y) in the third equality are utilized, where *X* and *Y* are random variables and *a* is a constant value.

sity function and the distribution function of *X*, respectively. Note that $F_x(x) = P(X \le x)$ and $f_x(x) = F'_x(x)$.

When $X = \psi(Y)$, we want to obtain the probability density function of *Y*. Let $f_y(y)$ and $F_y(y)$ be the probability density function and the distribution function of *Y*, respectively. In the case of $\psi'(X) > 0$, the distribution function of *Y*, $F_y(y)$, is rewritten as follows:

$$F_{y}(y) = P(Y \le y) = P(\psi(Y) \le \psi(y))$$
$$= P(X \le \psi(y)) = F_{x}(\psi(y)).$$
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The first equality is the definition of the cumulative distribution function. The second equality holds because of $\psi'(Y) >$ 0. Therefore, differentiating $F_y(y)$ with respect to y, we can obtain the following expression:

$$f_{y}(y) = F'_{y}(y) = \psi'(y)F'_{x}(\psi(y)) = \psi'(y)f_{x}(\psi(y)).$$
(4)

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Next, in the case of $\psi'(X) < 0$, the distribution function of *Y*, *F*_y(*y*), is rewritten as follows:

$$F_{y}(y) = P(Y \le y) = P(\psi(Y) \ge \psi(y)) = P(X \ge \psi(y))$$
$$= 1 - P(X < \psi(y)) = 1 - F_{x}(\psi(y)).$$

Thus, in the case of $\psi'(X) < 0$, pay attention to the second equality, where the inequality sign is reversed. Differentiating $F_y(y)$ with respect to *y*, we obtain the following result:

$$f_{y}(y) = F'_{y}(y) = -\psi'(y)F'_{x}(\psi(y)) = -\psi'(y)f_{x}(\psi(y)).$$
 (5)
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Note that $-\psi'(y) > 0$.

Thus, summarizing the above two cases, i.e., $\psi'(X) > 0$ and $\psi'(X) < 0$, equations (4) and (5) indicate the following result:

$$f_{y}(y) = |\psi'(y)| f_{x}(\psi(y)),$$

which is called the transformation of variables.

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Example 1.9: When $X \sim N(0, 1)$, we derive the probability density function of $Y = \mu + \sigma X$.

Since we have:

$$X = \psi(Y) = \frac{Y - \mu}{\sigma},$$

 $\psi'(y) = 1/\sigma$ is obtained. Therefore, $f_y(y)$ is given by:

$$f_{y}(y) = |\psi'(y)| f_{x}(\psi(y)) = \frac{1}{\sigma \sqrt{2\pi}} \exp\left(-\frac{1}{2\sigma^{2}}(y-\mu)^{2}\right),$$

which indicates the normal distribution with mean μ and variance σ^2 , denoted by $N(\mu, \sigma^2)$.

On Distribution of $Y = X^2$: As an example, when we know the distribution function of *X* as $F_x(x)$, we want to obtain the distribution function of *Y*, $F_y(y)$, where $Y = X^2$. Using $F_x(x)$, $F_y(y)$ is rewritten as follows:

$$\begin{split} F_y(y) &= P(Y \leq y) = P(X^2 \leq y) = P(-\sqrt{y} \leq X \leq \sqrt{y}) \\ &= F_x(\sqrt{y}) - F_x(-\sqrt{y}). \end{split}$$

The probability density function of *Y* is obtained as follows:

$$f_y(y) = F'_y(y) = \frac{1}{2\sqrt{y}} \Big(f_x(\sqrt{y}) + f_x(-\sqrt{y}) \Big).$$

4.2 Multivariate Cases

Bivariate Case: Let $f_{xy}(x, y)$ be a joint probability density function of *X* and *Y*. Let $X = \psi_1(U, V)$ and $Y = \psi_2(U, V)$ be a one-to-one transformation from (X, Y) to (U, V). Then, we obtain a joint probability density function of *U* and *V*, denoted by $f_{uv}(u, v)$, as follows:

$$f_{uv}(u,v) = |J| f_{xy}(\psi_1(u,v),\psi_2(u,v)),$$

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where J is called the **Jacobian** of the transformation, which

is defined as:

$$J = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \\ \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}.$$

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Multivariate Case: Let $f_x(x_1, x_2, \dots, x_n)$ be a joint probability density function of X_1, X_2, \dots, X_n . Suppose that a one-to-one transformation from (X_1, X_2, \dots, X_n) to (Y_1, Y_2, \dots, Y_n) is given by:

$$X_{1} = \psi_{1}(Y_{1}, Y_{2}, \dots, Y_{n}),$$

$$X_{2} = \psi_{2}(Y_{1}, Y_{2}, \dots, Y_{n}),$$

$$\vdots$$

$$X_{n} = \psi_{n}(Y_{1}, Y_{2}, \dots, Y_{n}).$$

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Then, we obtain a joint probability density function of Y_1 , Y_2, \dots, Y_n , denoted by $f_y(y_1, y_2, \dots, y_n)$, as follows:

$$f_{y}(y_{1}, y_{2}, \cdots, y_{n})$$

= $|J|f_{x}(\psi_{1}(y_{1}, \cdots, y_{n}), \psi_{2}(y_{1}, \cdots, y_{n}), \cdots, \psi_{n}(y_{1}, \cdots, y_{n})),$

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where J is called the Jacobian of the transformation, which is defined as:

	$\left \frac{\partial x_1}{\partial y_1} \right $	$\frac{\partial x_1}{\partial y_2}$		$\frac{\partial x_1}{\partial y_n}$
<i>J</i> =	$\frac{\partial x_2}{\partial y_1}$	$\frac{\partial x_2}{\partial y_2}$		$\frac{\partial x_2}{\partial y_n}$
	:	:	·	:
	$\left \frac{\partial x_n}{\partial y_1}\right $	$\frac{\partial x_n}{\partial y_2}$		$\left \frac{\partial x_n}{\partial y_n} \right $