8 Generalized Least Squares Method (GLS, 一般化最小自乗法)

1. Regression model: $y = X\beta + u, \qquad u \sim N(0, \sigma^2\Omega)$

2. **Heteroscedasticity (不等分散，不均一分散)**

$$\sigma^2\Omega = \begin{pmatrix} \sigma_1^2 & 0 & \cdots & 0 \\ 0 & \sigma_2^2 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & \sigma_n^2 \end{pmatrix}$$

First-Order Autocorrelation (一階の自己相関，系列相関)

In the case of time series data, the subscript is conventionally given by t, not i .

$u_t = \rho u_{t-1} + \epsilon_t, \qquad \epsilon_t \sim \text{ iid } N(0, \sigma_\epsilon^2)$

$$\sigma^2 \Omega = \frac{\sigma_\epsilon^2}{1-\rho^2} \begin{pmatrix} 1 & \rho & \rho^2 & \cdots & \rho^{n-1} \\ \rho & 1 & \rho & \cdots & \rho^{n-2} \\ \rho^2 & \rho & 1 & \cdots & \rho^{n-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \rho^{n-1} & \rho^{n-2} & \rho^{n-3} & \cdots & 1 \end{pmatrix}$$

$$\mathrm{V}(u_t) = \sigma^2 = \frac{\sigma_\epsilon^2}{1-\rho^2}$$

3. The Generalized Least Squares (GLS，一般化最小二乗法) estimator of β,

denoted by b, solves the following minimization problem:

$$\min_{b} \ (y - Xb)'\Omega^{-1}(y - Xb)$$

The GLSE of β is:

$$b = (X'\Omega^{-1}X)^{-1}X'\Omega^{-1}y$$

4. In general, when Ω is symmetric, Ω is decomposed as follows.

$$\Omega = A'\Lambda A$$

Λ is a diagonal matrix, where the diagonal elements of Λ are given by the eigen values.

A is a matrix consisting of eigen vectors.

When Ω is a positive definite matrix, all the diagonal elements of Λ are positive.

5. There exists P such that $\Omega = PP'$ (i.e., take $P = A'\Lambda^{1/2}$). $\Longrightarrow$ $P^{-1}\Omega P'^{-1} = I_n$

Multiply P^{-1} on both sides of $y = X\beta + u$.

We have:

$$y^\star = X^\star\beta + u^\star,$$

where $\quad y^\star = P^{-1}y, \quad X^\star = P^{-1}X, \quad$ and $\quad u^\star = P^{-1}u$.

The variance of $u^\star$ is:

$$\mathrm{V}(u^\star) = \mathrm{V}(P^{-1}u) = P^{-1}\mathrm{V}(u)P'^{-1} = \sigma^2 P^{-1}\Omega P'^{-1} = \sigma^2 I_n.$$

because $\Omega = PP'$, i.e., $P^{-1}\Omega P'^{-1} = I_n$.

Accordingly, the regression model is rewritten as:

$$y^\star = X^\star\beta + u^\star, \qquad u^\star \sim (0, \sigma^2 I_n)$$

Apply OLS to the above model.

Let b be as estimator of β from the above model.

That is, the minimization problem is given by:

$$\min_{b} \ (y^\star - X^\star b)'(y^\star - X^\star b),$$

which is equivalent to:

$$\min_{b} \ (y - Xb)'\Omega^{-1}(y - Xb).$$

Solving the minimization problem above, we have the following estimator:

$$b = (X^{\star\prime}X^\star)^{-1}X^{\star\prime}y^\star$$

$$= (X'\Omega^{-1}X)^{-1}X'\Omega^{-1}y,$$

which is called GLS (Generalized Least Squares) estimator.

b is rewritten as follows:

$$b = \beta + (X^{\star\prime}X^{\star})^{-1}X^{\star\prime}u^{\star} = \beta + (X'\Omega^{-1}X)^{-1}X'\Omega^{-1}u$$

The mean and variance of b are given by:

$$\mathrm{E}(b) = \beta,$$

$$\mathrm{V}(b) = \sigma^2(X^{\star\prime}X^{\star})^{-1} = \sigma^2(X'\Omega^{-1}X)^{-1}.$$

6. Suppose that the regression model is given by:

$$y = X\beta + u, \qquad u \sim N(0, \sigma^2\Omega).$$

In this case, when we use OLS, what happens?

$$\hat{\beta} = (X'X)^{-1}X'y = \beta + (X'X)^{-1}X'u$$

$$V(\hat{\beta}) = \sigma^2(X'X)^{-1}X'\Omega X(X'X)^{-1}$$

Compare GLS and OLS.

(a) Expectation:

$$E(\hat{\beta}) = \beta, \quad \text{and} \quad E(b) = \beta$$

Thus, both $\hat{\beta}$ and b are unbiased estimator.

(b) Variance:

$$V(\hat{\beta}) = \sigma^2(X'X)^{-1}X'\Omega X(X'X)^{-1}$$

$$V(b) = \sigma^2(X'\Omega^{-1}X)^{-1}$$

Which is more efficient, OLS or GLS?.

$$\begin{aligned}
\mathrm{V}(\hat\beta) - \mathrm{V}(b) &= \sigma^2 (X'X)^{-1} X'\Omega X (X'X)^{-1} - \sigma^2 (X'\Omega^{-1}X)^{-1} \\
&= \sigma^2 \Big((X'X)^{-1}X' - (X'\Omega^{-1}X)^{-1}X'\Omega^{-1} \Big) \Omega \\
&\qquad \times \Big((X'X)^{-1}X' - (X'\Omega^{-1}X)^{-1}X'\Omega^{-1} \Big)' \\
&= \sigma^2 A\Omega A'
\end{aligned}$$

Ω is the variance-covariance matrix of u, which is a positive definite matrix.

Therefore, except for $\Omega = I_n$, $A\Omega A'$ is also a positive definite matrix.

This implies that $\mathrm{V}(\hat\beta_i) - \mathrm{V}(b_i) > 0$ for the ith element of β.

Accordingly, b is more efficient than $\hat\beta$.

7. If $u \sim N(0, \sigma^2\Omega)$, then $b \sim N(\beta, \sigma^2(X'\Omega^{-1}X)^{-1})$.

Consider testing the hypothesis $H_0 : R\beta = r$.

$R: \ G \times k, \quad \text{rank}(R) = G \leq k.$

$Rb \sim N(R\beta, \sigma^2 R(X'\Omega^{-1}X)^{-1}R').$

Therefore, the following quadratic form is distributed as:

$$\frac{(Rb - r)'(R(X'\Omega^{-1}X)^{-1}R')^{-1}(Rb - r)}{\sigma^2} \sim \chi^2(G)$$

8. Because $(y^\star - X^\star b)'(y^\star - X^\star b)/\sigma^2 \sim \chi^2(n-k)$, we obtain:

$$\frac{(y - Xb)'\Omega^{-1}(y - Xb)}{\sigma^2} \sim \chi^2(n-k)$$

9. Furthermore, from the fact that b is independent of $y - Xb$, the following F distribution can be derived:

$$\frac{(Rb-r)'(R(X'\Omega^{-1}X)^{-1}R')^{-1}(Rb-r)/G}{(y-Xb)'\Omega^{-1}(y-Xb)/(n-k)} \sim F(G, n-k)$$

10. Let b be the unrestricted GLSE and $\tilde{b}$ be the restricted GLSE.

    Their residuals are given by e and $\tilde{u}$, respectively.

$$e = y - Xb, \qquad \tilde{u} = y - X\tilde{b}$$

    Then, the F test statistic is written as follows:

$$\frac{(\tilde{u}'\Omega^{-1}\tilde{u} - e'\Omega^{-1}e)/G}{e'\Omega^{-1}e/(n-k)} \sim F(G, n-k)$$

8.1 Example: Mixed Estimation (Theil and Goldberger Model)

A generalization of the restricted OLS $\Longrightarrow$ Stochastic linear restriction:

$$r = R\beta + v, \qquad \mathrm{E}(v) = 0 \text{ and } \mathrm{V}(v) = \sigma^2\Psi$$

$$y = X\beta + u, \qquad \mathrm{E}(u) = 0 \text{ and } \mathrm{V}(u) = \sigma^2 I_n$$

Using a matrix form,

$$\begin{pmatrix} y \\ r \end{pmatrix} = \begin{pmatrix} X \\ R \end{pmatrix}\beta + \begin{pmatrix} u \\ v \end{pmatrix}, \qquad \mathrm{E}\begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \text{ and } \mathrm{V}\begin{pmatrix} u \\ v \end{pmatrix} = \sigma^2\begin{pmatrix} I_n & 0 \\ 0 & \Psi \end{pmatrix}$$

For estimation, we do not need normality assumption.

Applying GLS, we obtain:

$$\begin{aligned} b &= \left(\begin{pmatrix} X' & R' \end{pmatrix} \begin{pmatrix} I_n & 0 \\ 0 & \Psi \end{pmatrix}^{-1} \begin{pmatrix} X \\ R \end{pmatrix} \right)^{-1} \left(\begin{pmatrix} X' & R' \end{pmatrix} \begin{pmatrix} I_n & 0 \\ 0 & \Psi \end{pmatrix}^{-1} \begin{pmatrix} y \\ r \end{pmatrix} \right) \\ &= \left(X'X + R'\Psi^{-1}R \right)^{-1} \left(X'y + R'\Psi^{-1}r \right). \end{aligned}$$

Mean and Variance of b: b is rewritten as follows:

$$b = \left(\begin{pmatrix} X' & R' \end{pmatrix} \begin{pmatrix} I_n & 0 \\ 0 & \Psi \end{pmatrix}^{-1} \begin{pmatrix} X \\ R \end{pmatrix} \right)^{-1} \left(\begin{pmatrix} X' & R' \end{pmatrix} \begin{pmatrix} I_n & 0 \\ 0 & \Psi \end{pmatrix}^{-1} \begin{pmatrix} y \\ r \end{pmatrix} \right)$$

$$= \beta + \left(\begin{pmatrix} X' & R' \end{pmatrix} \begin{pmatrix} I_n & 0 \\ 0 & \Psi \end{pmatrix}^{-1} \begin{pmatrix} X \\ R \end{pmatrix} \right)^{-1} \begin{pmatrix} u \\ v \end{pmatrix}$$

Therefore, the mean and variance are given by:

$$\mathrm{E}(b) = \beta \qquad \Longrightarrow \qquad b \text{ is unbiased.}$$

$$\mathrm{V}(b) = \sigma^2 \left(\begin{pmatrix} X' & R' \end{pmatrix} \begin{pmatrix} I_n & 0 \\ 0 & \Psi \end{pmatrix}^{-1} \begin{pmatrix} X \\ R \end{pmatrix} \right)^{-1}$$

$$= \sigma^2 \left(X'X + R'\Psi^{-1}R \right)^{-1}$$

9 Maximum Likelihood Estimation (MLE, 最尤法)

$\longrightarrow$ **Review**

1. The distribution function of $\{X_i\}_{i=1}^n$ is $f(x;\theta)$, where $x = (x_1, x_2, \cdots, x_n)$ and $\theta = (\mu, \Sigma)$.

   Note that X is a vector of random variables and x is a vector of their realizations (i.e., observed data).

   Likelihood function $L(\cdot)$ is defined as $L(\theta; x) = f(x;\theta)$.

   Note that $f(x;\theta) = \prod_{i=1}^n f(x_i;\theta)$ when X_1, X_2, $\cdots$, X_n are mutually independently and identically distributed.

The maximum likelihood estimator (MLE) of θ is θ such that:

$$\max_{\theta} \; L(\theta; X). \qquad \Longleftrightarrow \qquad \max_{\theta} \; \log L(\theta; X).$$

MLE satisfies the following two conditions:

(a) $\dfrac{\partial \log L(\theta; X)}{\partial \theta} = 0.$

(b) $\dfrac{\partial^2 \log L(\theta; X)}{\partial \theta \partial \theta'}$ is a negative definite matrix.

2. **Fisher's information matrix (フィッシャーの情報行列)** is defined as:

$$I(\theta) = -\mathrm{E}\Big(\frac{\partial^2 \log L(\theta; X)}{\partial \theta \partial \theta'}\Big),$$

where we have the following equality:

$$-\mathrm{E}\Big(\frac{\partial^2 \log L(\theta; X)}{\partial \theta \partial \theta'}\Big) = \mathrm{E}\Big(\frac{\partial \log L(\theta; X)}{\partial \theta} \frac{\partial \log L(\theta; X)}{\partial \theta'}\Big) = \mathrm{V}\Big(\frac{\partial \log L(\theta; X)}{\partial \theta}\Big)$$