

Substitute $a_i = 0$, $\mu_i = 0$, $b_i = \omega_i$ and $\sigma_i^2 = \sigma^2$.

Then, using the moment-generating function, $\sum_{i=1}^n \omega_i u_i$ is distributed as:

$$\sum_{i=1}^n \omega_i u_i \sim N(0, \sigma^2 \sum_{i=1}^n \omega_i^2).$$

Therefore, $\hat{\beta}_2$ is distributed as:

$$\hat{\beta}_2 = \beta_2 + \sum_{i=1}^n \omega_i u_i \sim N(\beta_2, \sigma^2 \sum_{i=1}^n \omega_i^2),$$

or equivalently,

$$\frac{\hat{\beta}_2 - \beta_2}{\sigma \sqrt{\sum_{i=1}^n \omega_i^2}} = \frac{\hat{\beta}_2 - \beta_2}{\sigma / \sqrt{\sum_{i=1}^n (x_i - \bar{x})^2}} \sim N(0, 1),$$

for any n .

[Review 1] t Distribution:

$Z \sim N(0, 1)$, $V \sim \chi^2(k)$, and Z is independent of V . Then, $\frac{Z}{\sqrt{V/k}} \sim t(k)$.

[End of Review 1]

[Review 2] t Distribution:

Suppose that X_1, X_2, \dots, X_n are mutually independently, identically and normally distributed with mean μ and variance σ^2 .

$\bar{X} \sim N(\mu, \sigma^2/n)$, i.e., $\frac{\bar{X} - \mu}{\sigma/\sqrt{n}} \sim N(0, 1)$.

Define $S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$, which is an unbiased estimator of σ^2 .

It is known that $\frac{(n-1)S^2}{\sigma^2} \sim \chi^2(n-1)$ and \bar{X} is independent of S^2 . (The proof is skipped.)

Then, we obtain $\frac{\frac{\bar{X} - \mu}{\sigma / \sqrt{n}}}{\sqrt{\frac{(n-1)S^2}{\sigma^2}} / (n-1)} = \frac{\bar{X} - \mu}{S / \sqrt{n}} \sim t(n-1)$.

As a result, replacing σ^2 by S^2 , $\frac{\bar{X} - \mu}{S / \sqrt{n}} \sim t(n-1)$.

[End of Review 2]

Back to OLS:

Replacing σ^2 by its estimator s^2 defined in (17), it is known that we have:

$$\frac{\hat{\beta}_2 - \beta_2}{s / \sqrt{\sum_{i=1}^n (x_i - \bar{x})^2}} \sim t(n - 2),$$

where $t(n - 2)$ denotes t distribution with $n - 2$ degrees of freedom.

Thus, under normality assumption on the error term u_i , the $t(n - 2)$ distribution is used for the confidence interval and the testing hypothesis in small sample.

Or, taking the square on both sides,

$$\left(\frac{\hat{\beta}_2 - \beta_2}{s / \sqrt{\sum_{i=1}^n (x_i - \bar{x})^2}} \right)^2 \sim F(1, n - 2),$$

which will be proved later.

Before going to **multiple regression model** (重回帰モデル),

2 Some Formulas of Matrix Algebra

1. Let $A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1k} \\ a_{21} & a_{22} & \cdots & a_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ a_{l1} & a_{l2} & \cdots & a_{lk} \end{pmatrix} = [a_{ij}]$,

which is a $l \times k$ matrix, where a_{ij} denotes i th row and j th column of A .

The **transposed matrix** (転置行列) of A , denoted by A' , is defined as:

$$A' = \begin{pmatrix} a_{11} & a_{21} & \cdots & a_{l1} \\ a_{12} & a_{22} & \cdots & a_{l2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1k} & a_{2k} & \cdots & a_{lk} \end{pmatrix} = [a_{ji}],$$

where the i th row of A' is the i th column of A .

$$2. (Ax)' = x'A',$$

where A and x are a $l \times k$ matrix and a $k \times 1$ vector, respectively.

$$3. a' = a,$$

where a denotes a scalar.

$$4. \frac{\partial a'x}{\partial x} = a,$$

where a and x are $k \times 1$ vectors.

$$5. \frac{\partial x'Ax}{\partial x} = (A + A')x,$$

where A and x are a $k \times k$ matrix and a $k \times 1$ vector, respectively.

Especially, when A is symmetric,

$$\frac{\partial x'Ax}{\partial x} = 2Ax.$$

6. Let A and B be $k \times k$ matrices, and I_k be a $k \times k$ **identity matrix** (單位行列) (one in the diagonal elements and zero in the other elements).

When $AB = I_k$, B is called the **inverse matrix** (逆行列) of A , denoted by $B = A^{-1}$.

That is, $AA^{-1} = A^{-1}A = I_k$.

7. Let A be a $k \times k$ matrix and x be a $k \times 1$ vector.

If A is a **positive definite matrix** (正值定符号行列), for any x except for $x = 0$ we have:

$$x'Ax > 0.$$

If A is a **positive semidefinite matrix** (非負值定符号行列), for any x except for $x = 0$ we have:

$$x'Ax \geq 0.$$

If A is a **negative definite matrix** (負値定符号行列), for any x except for $x = 0$ we have:

$$x'Ax < 0.$$

If A is a **negative semidefinite matrix** (非正值定符号行列), for any x except for $x = 0$ we have:

$$x'Ax \leq 0.$$

Trace, Rank and etc.: $A : k \times k,$ $B : n \times k,$ $C : k \times n.$

1. The **trace** (トレース) of A is: $\text{tr}(A) = \sum_{i=1}^k a_{ii}$, where $A = [a_{ij}]$.
2. The **rank** (ランク, 階数) of A is the maximum number of linearly independent column (or row) vectors of A , which is denoted by $\text{rank}(A)$.

3. If A is an **idempotent matrix** (べき等行列), $A = A^2$.
4. If A is an idempotent and symmetric matrix, $A = A^2 = A'A$.
5. A is idempotent if and only if the eigen values of A consist of 1 and 0.
6. If A is idempotent, $\text{rank}(A) = \text{tr}(A)$.
7. $\text{tr}(BC) = \text{tr}(CB)$

Distributions in Matrix Form:

1. Let X , μ and Σ be $k \times 1$, $k \times 1$ and $k \times k$ matrices.

When $X \sim N(\mu, \Sigma)$, the density function of X is given by:

$$f(x) = \frac{1}{(2\pi)^{k/2} |\Sigma|^{1/2}} \exp\left(-\frac{1}{2}(x - \mu)' \Sigma^{-1} (x - \mu)\right).$$

$$E(X) = \mu \text{ and } V(X) = E\left((X - \mu)(X - \mu)'\right) = \Sigma$$

The moment-generating function: $\phi(\theta) = E\left(\exp(\theta'X)\right) = \exp(\theta'\mu + \frac{1}{2}\theta'\Sigma\theta)$

(*) In the univariate case, when $X \sim N(\mu, \sigma^2)$, the density function of X is:

$$f(x) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp\left(-\frac{1}{2\sigma^2}(x - \mu)^2\right).$$

2. If $X \sim N(\mu, \Sigma)$, then $(X - \mu)'\Sigma^{-1}(X - \mu) \sim \chi^2(k)$.

Note that $X'X \sim \chi^2(k)$ when $X \sim N(0, I_k)$.

3. $X: n \times 1$, $Y: m \times 1$, $X \sim N(\mu_x, \Sigma_x)$, $Y \sim N(\mu_y, \Sigma_y)$

X is independent of Y , i.e., $E\left((X - \mu_x)(Y - \mu_y)'\right) = 0$ in the case of normal random variables.

$$\frac{(X - \mu_x)'\Sigma_x^{-1}(X - \mu_x)/n}{(Y - \mu_y)'\Sigma_y^{-1}(Y - \mu_y)/m} \sim F(n, m)$$

4. If $X \sim N(0, \sigma^2 I_n)$ and A is a symmetric idempotent $n \times n$ matrix of rank G , then $X'AX/\sigma^2 \sim \chi^2(G)$.

Note that $X'AX = (AX)'(AX)$ and $\text{rank}(A) = \text{tr}(A)$ because A is idempotent.

5. If $X \sim N(0, \sigma^2 I_n)$, A and B are symmetric idempotent $n \times n$ matrices of rank G and K , and $AB = 0$, then

$$\frac{X'AX/G}{\sigma^2} \bigg/ \frac{X'BX/K}{\sigma^2} = \frac{X'AX/G}{X'BX/K} \sim F(G, K).$$

3 Multiple Regression Model (重回帰モデル)

Up to now, only one independent variable, i.e., x_i , is taken into the regression model. We extend it to more independent variables, which is called the **multiple regression model** (重回帰モデル).

We consider the following regression model:

$$y_i = \beta_1 x_{i,1} + \beta_2 x_{i,2} + \cdots + \beta_k x_{i,k} + u_i = (x_{i,1}, x_{i,2}, \cdots, x_{i,k}) \begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{pmatrix} + u_i = x_i \beta + u_i,$$

for $i = 1, 2, \cdots, n$, where x_i and β denote a $1 \times k$ vector of the independent variables

and a $k \times 1$ vector of the unknown parameters to be estimated, which are given by:

$$x_i = (x_{i,1}, x_{i,2}, \dots, x_{i,k}), \quad \beta = \begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{pmatrix}.$$

$x_{i,j}$ denotes the i th observation of the j th independent variable.

The case of $k = 2$ and $x_{i,1} = 1$ for all i is exactly equivalent to (1).

Therefore, the matrix form above is a generalization of (1).

Writing all the equations for $i = 1, 2, \dots, n$, we have:

$$y_1 = \beta_1 x_{1,1} + \beta_2 x_{1,2} + \dots + \beta_k x_{1,k} + u_1 = x_1 \beta + u_1,$$

$$y_2 = \beta_1 x_{2,1} + \beta_2 x_{2,2} + \dots + \beta_k x_{2,k} + u_2 = x_2 \beta + u_2,$$

$$\vdots$$

$$y_n = \beta_1 x_{n,1} + \beta_2 x_{n,2} + \dots + \beta_k x_{n,k} + u_n = x_n \beta + u_n,$$

which is rewritten as:

$$\begin{aligned} \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} &= \begin{pmatrix} x_{1,1} & x_{1,2} & \cdots & x_{1,k} \\ x_{2,1} & x_{2,2} & \cdots & x_{2,k} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n,1} & x_{n,2} & \cdots & x_{n,k} \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{pmatrix} + \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix} \\ &= \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \beta + \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix}. \end{aligned}$$

Again, the above equation is compactly rewritten as:

$$y = X\beta + u, \tag{18}$$

where y , X and u are denoted by:

$$y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}, \quad X = \begin{pmatrix} x_{1,1} & x_{1,2} & \cdots & x_{1,k} \\ x_{2,1} & x_{2,2} & \cdots & x_{2,k} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n,1} & x_{n,2} & \cdots & x_{n,k} \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}, \quad u = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix}.$$

Utilizing the matrix form (18), we derive the ordinary least squares estimator of β , denoted by $\hat{\beta}$.

In (18), replacing β by $\hat{\beta}$, we have the following equation:

$$y = X\hat{\beta} + e,$$

where e denotes a $n \times 1$ vector of the residuals.

The i th element of e is given by e_i .