

8.3 GLS — Review

Regression model:

$$y = X\beta + u, \quad u \sim N(0, \Omega),$$

where y , X , β , u , 0 and Ω are $n \times 1$, $n \times k$, $k \times 1$, $n \times 1$, $n \times 1$, and $n \times n$, respectively.

We solve the following minimization problem:

$$\min_{\beta} (y - X\beta)' \Omega^{-1} (y - X\beta).$$

Let b be a solution of the above minimization problem.

GLS estimator of β is given by:

$$b = (X' \Omega^{-1} X)^{-1} X' \Omega^{-1} y.$$

In general, when Ω is symmetric, Ω is decomposed as follows.

$$\Omega = A' \Lambda A$$

Λ is a diagonal matrix, where the diagonal elements of Λ are given by the eigen values.

A is a matrix consisting of eigen vectors.

When Ω is a positive definite matrix, all the diagonal elements of Λ are positive.

There exists P such that $\Omega = PP'$ (i.e., take $P = A'\Lambda^{1/2}$). $\implies P^{-1}\Omega P'^{-1} = I_n$

Multiply P^{-1} on both sides of $y = X\beta + u$.

We have:

$$y^* = X^*\beta + u^*,$$

where $y^* = P^{-1}y$, $X^* = P^{-1}X$, and $u^* = P^{-1}u$.

The variance of u^* is:

$$V(u^*) = V(P^{-1}u) = P^{-1}V(u)P'^{-1} = \sigma^2 P^{-1}\Omega P'^{-1} = \sigma^2 I_n.$$

because $\Omega = PP'$, i.e., $P^{-1}\Omega P'^{-1} = I_n$.

Accordingly, the regression model is rewritten as:

$$y^* = X^*\beta + u^*, \quad u^* \sim (0, \sigma^2 I_n)$$

Apply OLS to the above model.

Let b be as estimator of β from the above model.

That is, the minimization problem is given by:

$$\min_b (y^* - X^*b)'(y^* - X^*b),$$

which is equivalent to:

$$\min_b (y - Xb)' \Omega^{-1} (y - Xb).$$

Solving the minimization problem above, we have the following estimator:

$$\begin{aligned} b &= (X^{*\prime}X^*)^{-1}X^{*\prime}y^* \\ &= (X'\Omega^{-1}X)^{-1}X'\Omega^{-1}y, \end{aligned}$$

which is called GLS (Generalized Least Squares) estimator.

b is rewritten as follows:

$$b = \beta + (X^{*\prime}X^*)^{-1}X^{*\prime}u^* = \beta + (X'\Omega^{-1}X)^{-1}X'\Omega^{-1}u$$

The mean and variance of b are given by:

$$E(b) = \beta,$$

$$V(b) = \sigma^2(X^{*\prime}X^*)^{-1} = \sigma^2(X'\Omega^{-1}X)^{-1}.$$

Suppose that the regression model is given by:

$$y = X\beta + u, \quad u \sim N(0, \sigma^2\Omega).$$

In this case, when we use OLS, what happens?

$$\hat{\beta} = (X'X)^{-1}X'y = \beta + (X'X)^{-1}X'u$$

$$V(\hat{\beta}) = \sigma^2(X'X)^{-1}X'\Omega X(X'X)^{-1}$$

● Compare GLS and OLS.

Expectation:

$$E(\hat{\beta}) = \beta, \quad \text{and} \quad E(b) = \beta$$

Thus, both $\hat{\beta}$ and b are unbiased estimator.

Variance:

$$V(\hat{\beta}) = \sigma^2(X'X)^{-1}X'\Omega X(X'X)^{-1}$$

$$V(b) = \sigma^2(X'\Omega^{-1}X)^{-1}$$

Which is more efficient, OLS or GLS?.

$$\begin{aligned}V(\hat{\beta}) - V(b) &= \sigma^2(X'X)^{-1}X'\Omega X(X'X)^{-1} - \sigma^2(X'\Omega^{-1}X)^{-1} \\ &= \sigma^2\left((X'X)^{-1}X' - (X'\Omega^{-1}X)^{-1}X'\Omega^{-1}\right)\Omega \\ &\quad \times\left((X'X)^{-1}X' - (X'\Omega^{-1}X)^{-1}X'\Omega^{-1}\right)' \\ &= \sigma^2A\Omega A'\end{aligned}$$

Ω is the variance-covariance matrix of u , which is a positive definite matrix.

Therefore, except for $\Omega = I_n$, $A\Omega A'$ is also a positive definite matrix.

This implies that $V(\hat{\beta}_i) - V(b_i) > 0$ for the i th element of β .

Accordingly, b is more efficient than $\hat{\beta}$.

If $u \sim N(0, \sigma^2\Omega)$, then $b \sim N(\beta, \sigma^2(X'\Omega^{-1}X)^{-1})$.

● Maximum Likelihood Estimation (MLE):

$$y = X\beta + u, \quad u \sim N(0, \sigma^2\Omega).$$

$E(y) = X\beta$ and $V(y) = \sigma^2\Omega$

$$f(y) = (2\pi\sigma^2)^{-n/2} |\Omega|^{-1/2} \exp\left(-\frac{1}{2\sigma^2}(y - X\beta)\Omega^{-1}(y - X\beta)'\right) = L(\beta, \sigma^2)$$

b is equivalent to MLE.

8.4 Panel Model Basic

Model:

$$y_{it} = X_{it}\beta + v_i + u_{it}, \quad i = 1, 2, \dots, n, \quad t = 1, 2, \dots, T$$

where i indicates individual and t denotes time.

There are n observations for each t .

u_{it} indicates the error term, assuming that $E(u_{it}) = 0$, $V(u_{it}) = \sigma_u^2$ and $\text{Cov}(u_{it}, u_{js}) = 0$ for $i \neq j$ and $t \neq s$.

v_i denotes the individual effect, which is fixed or random.

8.4.1 Fixed Effect Model (固定効果モデル)

In the case where v_i is fixed, the case of $v_i = z_i\alpha$ is included.

$$y_{it} = X_{it}\beta + v_i + u_{it}, \quad i = 1, 2, \dots, n, \quad t = 1, 2, \dots, T,$$

$$\bar{y}_i = \bar{X}_i\beta + v_i + \bar{u}_i, \quad i = 1, 2, \dots, n,$$

where $\bar{y}_i = \frac{1}{T} \sum_{t=1}^T y_{it}$, $\bar{X}_i = \frac{1}{T} \sum_{t=1}^T X_{it}$, and $\bar{u}_i = \frac{1}{T} \sum_{t=1}^T u_{it}$.

$$(y_{it} - \bar{y}_i) = (X_{it} - \bar{X}_i)\beta + (u_{it} - \bar{u}_i), \quad i = 1, 2, \dots, n, \quad t = 1, 2, \dots, T,$$

Taking an example of y , the left-hand side of the above equation is rewritten as:

$$y_{it} - \bar{y}_i = y_{it} - \frac{1}{T} 1'_T y_i,$$

where $1_T = \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix}$, which is a $T \times 1$ vector, and $y_i = \begin{pmatrix} y_{i1} \\ y_{i2} \\ \vdots \\ y_{iT} \end{pmatrix}$.

$$\begin{pmatrix} y_{i1} - \bar{y}_i \\ y_{i2} - \bar{y}_i \\ \vdots \\ y_{iT} - \bar{y}_i \end{pmatrix} = I_T y_i - 1_T \bar{y}_i = I_T y_i - \frac{1}{T} 1_T 1_T' y_i = (I_T - \frac{1}{T} 1_T 1_T') y_i$$

Thus,

$$\begin{pmatrix} y_{i1} - \bar{y}_i \\ y_{i2} - \bar{y}_i \\ \vdots \\ y_{iT} - \bar{y}_i \end{pmatrix} = \begin{pmatrix} X_{i1} - \bar{X}_i \\ X_{i2} - \bar{X}_i \\ \vdots \\ X_{iT} - \bar{X}_i \end{pmatrix} \beta + \begin{pmatrix} u_{i1} - \bar{u}_i \\ u_{i2} - \bar{u}_i \\ \vdots \\ u_{iT} - \bar{u}_i \end{pmatrix}, \quad i = 1, 2, \dots, n,$$

which is re-written as:

$$(I_T - \frac{1}{T}1_T1_T')y_i = (I_T - \frac{1}{T}1_T1_T')X_i\beta + (I_T - \frac{1}{T}1_T1_T')u_i, \quad i = 1, 2, \dots, n,$$

i.e.,

$$D_T y_i = D_T X_i \beta + D_T u_i, \quad i = 1, 2, \dots, n,$$

where $D_T = (I_T - \frac{1}{T}1_T1_T')$, which is a $T \times T$ matrix.

Note that $D_T D_T' = D_T$, i.e., D_T is a symmetric and idempotent matrix.

Using the matrix form for $i = 1, 2, \dots, n$, we have:

$$\begin{pmatrix} D_T y_1 \\ D_T y_2 \\ \vdots \\ D_T y_n \end{pmatrix} = \begin{pmatrix} D_T X_1 \\ D_T X_2 \\ \vdots \\ D_T X_n \end{pmatrix} \beta + \begin{pmatrix} D_T u_1 \\ D_T u_2 \\ \vdots \\ D_T u_n \end{pmatrix},$$