

θ is a $k \times 1$ parameter vector to be estimated.

w_t is an observed vector $w_t = (y_t, x_t)$.

$h(\theta; w_t)$ is a $r \times 1$ vector function, where $r \geq k$.

Define $g(\theta; W_T)$ as follows:

$$g(\theta; W_T) = \frac{1}{T} \sum_{t=1}^T h(\theta; w_t),$$

where $W_T = \{w_T, w_{T-1}, \dots, w_1\}$.

Compute:

$$\min_{\theta} g(\theta; W_T)' S^{-1} g(\theta; W_T)$$

The solution of θ , denoted by $\hat{\theta}_T$, corresponds to the GMM estimator, where S is defined as follows:

$$S = \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \sum_{\tau=-\infty}^{\infty} E(h(\theta; w_t) h(\theta; w_{t-\tau})').$$

In empirical studies, S is replaced by its estimate, i.e., \hat{S}_T .

When $h(\theta; w_t)$, $t = 1, 2, \dots, T$, are not serially correlated, the following \hat{S}_T is consistent, i.e.,

$$\hat{S}_T = \frac{1}{T} \sum_{t=1}^T h(\hat{\theta}_T; w_t)h(\hat{\theta}_T; w_t)' \longrightarrow S.$$

When $h(\theta; w_t)$, $t = 1, 2, \dots, T$, are serially correlated,

$$\hat{S}_T = \hat{\Gamma}(0) + \sum_{\tau=1}^q k\left(\frac{\tau}{q+1}\right)(\hat{\Gamma}(\tau) + \hat{\Gamma}(\tau)'),$$

where $\hat{\Gamma}(\tau) = \frac{1}{T} \sum_{t=\tau+1}^T h(\hat{\theta}_T; w_t)h(\hat{\theta}_T; w_{t-\tau})'$.

$k(x) = 1 - x \implies$ Bartlett kernel (Newwey-west estimator),

$k(x) \implies$ Parzen kernel, and etc.

Then, we obtain:

$$\sqrt{T}(\hat{\theta}_T - \theta) \longrightarrow N\left(0, (DS^{-1}D')^{-1}\right),$$

where

$$D = \frac{\partial g(\theta; W_T)}{\partial \theta'}.$$

Note that D is a $r \times k$ matrix.

Let \hat{D}_T be an estimate of D .

The variance estimator of $\hat{\theta}_T$ is given by:

$$\hat{D}_T = \frac{\partial g(\hat{\theta}_T; W_T)}{\partial \theta'}.$$

Asymptotic Normality:

Assumption 1 : $\hat{\theta}_T \rightarrow \theta$,

Assumption 2 : $\sqrt{T}g(\theta; W_T) \rightarrow N(0, S)$.

Then, we have the following first-order approximation:

$$\begin{aligned} g(\theta; W_T) &\approx g(\hat{\theta}_T; W_T) + \frac{\partial g(\hat{\theta}_T; W_T)}{\partial \theta'}(\theta - \hat{\theta}_T) \\ &= g(\hat{\theta}_T; W_T) + \hat{D}_T(\theta - \hat{\theta}_T), \end{aligned}$$

where $g(\theta; W_T)$ is linearized around $\theta = \hat{\theta}_T$.

The first-order condition for the minimization problem is:

$$\left(\frac{\partial g(\theta; W_T)}{\partial \theta'} \right)' S^{-1} (g(\theta; W_T)) = 0.$$

Substituting the approximation into the above equation, we obtain the following:

$$\begin{aligned} D'S^{-1}\left(g(\theta; W_T)\right) &= D'S^{-1}\left(g(\hat{\theta}_T; W_T) + \hat{D}_T(\theta - \hat{\theta}_T)\right) \\ &= D'S^{-1}g(\hat{\theta}_T; W_T) + D'S^{-1}\hat{D}_T(\theta - \hat{\theta}_T). \end{aligned}$$

Therefore,

$$\sqrt{T}(\hat{\theta}_T - \theta) \approx (D'S^{-1}\hat{D}_T)^{-1}D'S^{-1}\sqrt{T}\left(g(\hat{\theta}_T; W_T) - g(\theta; W_T)\right).$$

Thus, GMM estimator, $\hat{\theta}_T$, has the following asymptotic distribution:

$$\sqrt{T}(\hat{\theta}_T - \theta) \longrightarrow N\left(0, (D'S^{-1}D)^{-1}\right),$$

where $\hat{D}_T \longrightarrow D$ is utilized.

From Assumption 2, we have the following asymptotic distribution:

$$\left(\sqrt{T}g(\theta; W_T)\right)' S^{-1}\left(\sqrt{T}g(\theta; W_T)\right) \longrightarrow \chi^2(r).$$

When θ is replaced by GMM estimator $\hat{\theta}_T$, we have the following distribution:

$$\left(\sqrt{T}g(\hat{\theta}_T; W_T)\right)' \hat{S}_T^{-1} \left(\sqrt{T}g(\hat{\theta}_T; W_T)\right) \longrightarrow \chi^2(r - k),$$

which is called a test of the overidentifying restrictions.

$\implies J$ test by Hansen (1982)

k linear combinations consisting of a $r \times 1$ vector $g(\hat{\theta}_T; W_T)$ are zeros.

Therefore, the degrees of freedom are $r - k$.

Some Examples:

(a) **OLS:**

Regression Model: $y_t = x_t\beta + \epsilon_t$, $E(x_t\epsilon_t) = 0$

$h(\theta; w_t)$ is taken as:

$$h(\theta; w_t) = x_t(y_t - x_t\beta).$$

(b) **IV (Instrumental Variable, 操作变数法):**

Regression Model: $y_t = x_t\beta + \epsilon_t$, $E(x_t\epsilon_t) \neq 0$, $E(z_t\epsilon_t) = 0$

$h(\theta; w_t)$ is taken as:

$$h(\theta; w_t) = z_t(y_t - x_t\beta),$$

where z_t is a vector of instrumental variables.

(c) **NLS (Nonlinear Least Squares, 非線形最小二乘法):**

Regression Model: $f(y_t, x_t, \beta) = \epsilon_t$, $E(x_t\epsilon_t) \neq 0$, $E(z_t\epsilon_t) = 0$

$h(\theta; w_t)$ is taken as:

$$h(\theta; w_t) = z_t f(y_t, x_t, \beta)$$

where z_t is a vector of instrumental variables.

Example: Demand function using STATA

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year
y = 実収入（一月当たり，実質データ）
q1 = 穀類支出額（一年当たり，実質データ）
p1 = 穀類価格（相対価格=穀類CPI / 総合CPI）
p2 = 魚介類価格（相対価格=魚介類CPI / 総合CPI）
p3 = 肉類価格（相対価格=肉類CPI / 総合CPI）

| year | y | q1 | p1 | p2 | p3 |
|------|--------|--------|----------|----------|----------|
| 2000 | 567865 | 7087.0 | 1.043390 | 0.884965 | 0.818365 |
| 2001 | 561722 | 6993.1 | 1.032520 | 0.886179 | 0.822154 |
| 2002 | 553768 | 6934.4 | 1.031800 | 0.891282 | 0.834872 |
| 2003 | 539928 | 6816.8 | 1.050410 | 0.876543 | 0.843621 |
| 2004 | 547006 | 6651.6 | 1.089510 | 0.865226 | 0.868313 |
| 2005 | 541367 | 6615.8 | 1.020640 | 0.862745 | 0.887513 |
| 2006 | 540863 | 6523.7 | 1.000000 | 0.878601 | 0.891975 |
| 2007 | 543994 | 6680.5 | 0.994856 | 0.886831 | 0.908436 |
| 2008 | 541821 | 6494.7 | 1.043610 | 0.894523 | 0.932049 |
| 2009 | 533154 | 6477.3 | 1.066870 | 0.898148 | 0.934156 |
| 2010 | 539577 | 6458.2 | 1.040420 | 0.889119 | 0.924352 |
| 2011 | 529750 | 6448.4 | 1.025960 | 0.894081 | 0.925234 |
| 2012 | 538988 | 6377.6 | 1.057170 | 0.904366 | 0.917879 |
| 2013 | 542018 | 6360.7 | 1.047620 | 0.909938 | 0.916149 |
| 2014 | 523953 | 6174.6 | 1.016130 | 0.971774 | 0.960685 |
| 2015 | 525669 | 6268.0 | 1.000000 | 1.000000 | 1.000000 |
| 2016 | 527501 | 6244.8 | 1.018020 | 1.019020 | 1.017020 |

2017 531693 6106.6 1.027890 1.066730 1.025900

```
. tsset year
      time variable: year, 2000 to 2017
      delta: 1 unit
```

```
. reg q1 y p1 p2 p3 if year>2000.5
```

| Source | SS | df | MS | Number of obs | = | 17 |
|----------|------------|----|------------|---------------|---|--------|
| Model | 913640.443 | 4 | 228410.111 | F(4, 12) | = | 25.83 |
| Residual | 106100.077 | 12 | 8841.67308 | Prob > F | = | 0.0000 |
| | | | | R-squared | = | 0.8960 |
| | | | | Adj R-squared | = | 0.8613 |
| Total | 1019740.52 | 16 | 63733.7825 | Root MSE | = | 94.03 |

| q1 | Coef. | Std. Err. | t | P> t | [95% Conf. Interval] | |
|-------|-----------|-----------|-------|-------|----------------------|-----------|
| y | .0067843 | .0045443 | 1.49 | 0.161 | -.003117 | .0166856 |
| p1 | -1128.834 | 998.7698 | -1.13 | 0.280 | -3304.966 | 1047.299 |
| p2 | 356.8095 | 806.2301 | 0.44 | 0.666 | -1399.815 | 2113.434 |
| p3 | -3442.221 | 1130.078 | -3.05 | 0.010 | -5904.448 | -979.9931 |
| _cons | 6850.563 | 3179.316 | 2.15 | 0.052 | -76.57278 | 13777.7 |

```
. gmm (q1-{b0}-{b1}*y-{b2}*p1-{b3}*p2-{b4}*p3) if year>2000.5, instruments(y p1
> p2 p3)
```

Step 1

Iteration 0: GMM criterion $Q(b) = 42400764$
 Iteration 1: GMM criterion $Q(b) = 6.781e-12$
 Iteration 2: GMM criterion $Q(b) = 6.781e-12$ (backed up)

Step 2

Iteration 0: GMM criterion $Q(b) = 1.966e-15$
 Iteration 1: GMM criterion $Q(b) = 1.963e-15$ (backed up)
 convergence not achieved

The Gauss-Newton stopping criterion has been met but missing standard errors indicate some of the parameters are not identified.

GMM estimation

Number of parameters = 5
 Number of moments = 5
 Initial weight matrix: Unadjusted Number of obs = 17
 GMM weight matrix: Robust

| | Coef. | Robust Std. Err. | z | P> z | [95% Conf. Interval] | |
|-----|-----------|------------------|-------|-------|----------------------|----------|
| /b0 | 6850.563 | 17645.71 | 0.39 | 0.698 | -27734.4 | 41435.53 |
| /b1 | .0067843 | .0282325 | 0.24 | 0.810 | -.0485504 | .062119 |
| /b2 | -1128.834 | 1057.915 | -1.07 | 0.286 | -3202.309 | 944.6415 |
| /b3 | 356.8095 | 1565.86 | 0.23 | 0.820 | -2712.219 | 3425.838 |
| /b4 | -3442.221 | 5085.561 | -0.68 | 0.498 | -13409.74 | 6525.296 |

Instruments for equation 1: y p1 p2 p3 _cons
 Warning: convergence not achieved

```
. gmm (q1-{b0}-{b1}*y-{b2}*p1-{b3}*p2-{b4}*p3) if year>2000.5, instruments(p1 p2
> p3 l.p1 l.p2 l.p3)
```

Step 1

```
Iteration 0: GMM criterion Q(b) = 42404066
Iteration 1: GMM criterion Q(b) = 2790.3146
Iteration 2: GMM criterion Q(b) = 2790.3146
```

Step 2

```
Iteration 0: GMM criterion Q(b) = .3201826
Iteration 1: GMM criterion Q(b) = .2469289
Iteration 2: GMM criterion Q(b) = .2469289
```

GMM estimation

```
Number of parameters = 5
Number of moments = 7
Initial weight matrix: Unadjusted Number of obs = 17
GMM weight matrix: Robust
```

| | Coef. | Robust Std. Err. | z | P> z | [95% Conf. Interval] | |
|-----|-----------|------------------|-------|-------|----------------------|----------|
| /b0 | -1192.466 | 4669.012 | -0.26 | 0.798 | -10343.56 | 7958.63 |
| /b1 | .0186312 | .0067682 | 2.75 | 0.006 | .0053657 | .0318967 |

| | | | | | | |
|-----|-----------|----------|-------|-------|-----------|----------|
| /b2 | -1016.864 | 780.979 | -1.30 | 0.193 | -2547.554 | 513.8271 |
| /b3 | -905.5585 | 598.0885 | -1.51 | 0.130 | -2077.79 | 266.6734 |
| /b4 | -499.8064 | 1147.985 | -0.44 | 0.663 | -2749.815 | 1750.202 |

Instruments for equation 1: p1 p2 p3 L.p1 L.p2 L.p3 _cons

. estat overid

Test of overidentifying restriction:

Hansen's J $\chi^2(2) = 4.19779$ (p = 0.1226)