Accordingly, b is more efficient than  $\hat{\beta}$ .

7. If  $u \sim N(0, \sigma^2 \Omega)$ , then  $b \sim N(\beta, \sigma^2 (X' \Omega^{-1} X)^{-1})$ .

Consider testing the hypothesis  $H_0: R\beta = r$ .

$$R: G \times k, \quad \operatorname{rank}(R) = G \le k.$$
$$Rb \sim N(R\beta, \sigma^2 R(X'\Omega^{-1}X)^{-1}R').$$

Therefore, the following quadratic form is distributed as:

$$\frac{(Rb-r)'(R(X'\Omega^{-1}X)^{-1}R')^{-1}(Rb-r)}{\sigma^2} \sim \chi^2(G)$$

8. Because  $(y^* - X^*b)'(y^* - X^*b)/\sigma^2 \sim \chi^2(n-k)$ , we obtain:

$$\frac{(y-Xb)'\Omega^{-1}(y-Xb)}{\sigma^2} \sim \chi^2(n-k)$$

9. Furthermore, from the fact that *b* is independent of y - Xb, the following *F* distribution can be derived:

$$\frac{(Rb-r)'(R(X'\Omega^{-1}X)^{-1}R')^{-1}(Rb-r)/G}{(y-Xb)'\Omega^{-1}(y-Xb)/(n-k)} \sim F(G,n-k)$$

10. Let *b* be the unrestricted GLSE and  $\tilde{b}$  be the restricted GLSE.

Their residuals are given by e and  $\tilde{u}$ , respectively.

$$e = y - Xb,$$
  $\tilde{u} = y - X\tilde{b}$ 

Then, the *F* test statistic is written as follows:

$$\frac{(\tilde{u}'\Omega^{-1}\tilde{u}-e'\Omega^{-1}e)/G}{e'\Omega^{-1}e/(n-k)} \sim F(G,n-k)$$

## 8.1 Example: Mixed Estimation (Theil and Goldberger Model)

A generalization of the restricted OLS  $\implies$  Stochastic linear restriction:

$$r = R\beta + v, \qquad E(v) = 0 \text{ and } V(v) = \sigma^2 \Psi$$
$$y = X\beta + u, \qquad E(u) = 0 \text{ and } V(u) = \sigma^2 I_n$$

Using a matrix form,

$$\binom{y}{r} = \binom{X}{R}\beta + \binom{u}{v}, \qquad E\binom{u}{v} = \binom{0}{0} \text{ and } V\binom{u}{v} = \sigma^2\binom{I_n \quad 0}{0 \quad \Psi}$$

For estimation, we do not need normality assumption.

Applying GLS, we obtain:

$$b = \left( (X' \quad R') \begin{pmatrix} I_n & 0 \\ 0 & \Psi \end{pmatrix}^{-1} \begin{pmatrix} X \\ R \end{pmatrix} \right)^{-1} \left( (X' \quad R') \begin{pmatrix} I_n & 0 \\ 0 & \Psi \end{pmatrix}^{-1} \begin{pmatrix} y \\ r \end{pmatrix} \right)$$
$$= \left( X'X + R'\Psi^{-1}R \right)^{-1} \left( X'y + R'\Psi^{-1}r \right).$$

Mean and Variance of *b*: *b* is rewritten as follows:

$$b = \left( \begin{pmatrix} X' & R' \end{pmatrix} \begin{pmatrix} I_n & 0 \\ 0 & \Psi \end{pmatrix}^{-1} \begin{pmatrix} X \\ R \end{pmatrix} \right)^{-1} \left( \begin{pmatrix} X' & R' \end{pmatrix} \begin{pmatrix} I_n & 0 \\ 0 & \Psi \end{pmatrix}^{-1} \begin{pmatrix} y \\ r \end{pmatrix} \right)$$
$$= \beta + \left( \begin{pmatrix} X' & R' \end{pmatrix} \begin{pmatrix} I_n & 0 \\ 0 & \Psi \end{pmatrix}^{-1} \begin{pmatrix} X \\ R \end{pmatrix} \right)^{-1} \begin{pmatrix} u \\ v \end{pmatrix}$$

Therefore, the mean and variance are given by:

$$E(b) = \beta \implies b \text{ is unbiased.}$$

$$\begin{split} \mathbf{V}(b) &= \sigma^2 \left( (X' \quad R') \begin{pmatrix} I_n & 0\\ 0 & \Psi \end{pmatrix}^{-1} \begin{pmatrix} X\\ R \end{pmatrix} \right)^{-1} \\ &= \sigma^2 \big( X'X + R' \Psi^{-1}R \big)^{-1} \end{split}$$

## 9 Maximum Likelihood Estimation (MLE, 載光法) → Review

1. The distribution function of  $\{X_i\}_{i=1}^n$  is  $f(x; \theta)$ , where  $x = (x_1, x_2, \dots, x_n)$ .  $\theta$  is a vector or matrix of unknown parameters, e.g.,  $\theta = (\mu, \Sigma)$ , where  $\mu = E(X_i)$ 

and  $\Sigma = V(X_i)$ .

Note that *X* is a vector of random variables and *x* is a vector of their realizations (i.e., observed data).

Likelihood function  $L(\cdot)$  is defined as  $L(\theta; x) = f(x; \theta)$ .

Note that  $f(x; \theta) = \prod_{i=1}^{n} f(x_i; \theta)$  when  $X_1, X_2, \dots, X_n$  are mutually independently and identically distributed.

The maximum likelihood estimate (MLE) of  $\theta$  is the  $\theta$  such that:

$$\max_{\theta} L(\theta; x). \qquad \Longleftrightarrow \qquad \max_{\theta} \log L(\theta; x).$$

Thus, MLE satisfies the following two conditions:

(a) 
$$\frac{\partial \log L(\theta; x)}{\partial \theta} = 0.$$
  $\implies$  Solution of  $\theta$ :  $\tilde{\theta} = \tilde{\theta}(x)$   
(b)  $\frac{\partial^2 \log L(\theta; x)}{\partial \theta \partial \theta'}$  is a negative definite matrix.

2.  $x = (x_1, x_2, \dots, x_n)$  are used as the observations (i.e., observed data).

 $X = (X_1, X_2, \dots, X_n)$  denote the random variables associated with the joint distribution  $f(x; \theta) = \prod_{i=1}^n f(x_i; \theta)$ .