

Therefore,

$$\frac{1}{T^2} \sum_{t=1}^T y_{t-1}^2 \longrightarrow \text{a distribution.}$$

6. Summarizing the results up to now,  $T(\hat{\phi}_1 - \phi_1)$ , not  $\sqrt{T}(\hat{\phi}_1 - \phi_1)$ , has limiting distribution in the case of  $\phi_1 = 1$ .

$$T(\hat{\phi}_1 - \phi_1) = \frac{(1/T) \sum y_{t-1} \epsilon_t}{(1/T^2) \sum y_{t-1}^2} \longrightarrow \text{a distribution.}$$

The distributions of the  $t$  statistic:  $\frac{\hat{\phi}_1 - 1}{s_\phi}$ , where  $s_\phi$  denotes the standard error of  $\hat{\phi}_1$ .

$\implies$  Compare  $t$  distribution with (a) – (c).

$\implies$  **Unit Root Test (単位根検定, or Dickey-Fuller (DF) Test)**

$$y_t = \phi_1 y_{t-1} + \epsilon_t.$$

Test  $H_0 : \phi_1 = 1$  against  $H_1 : \phi_1 < 1$ .

Equivalently,

$$\Delta y_t = \rho y_{t-1} + \epsilon_t.$$

Test  $H_0 : \rho = 0$  against  $H_1 : \rho < 0$ .

***t* Distribution**

<i>T</i>	0.010	0.025	0.050	0.100	0.900	0.950	0.975	0.990
25	-2.49	-2.06	-1.71	-1.32	1.32	1.71	2.06	2.49
50	-2.40	-2.01	-1.68	-1.30	1.30	1.68	2.01	2.40
100	-2.36	-1.98	-1.66	-1.29	1.29	1.66	1.98	2.36
250	-2.34	-1.97	-1.65	-1.28	1.28	1.65	1.97	2.34
500	-2.33	-1.96	-1.65	-1.28	1.28	1.65	1.96	2.33
$\infty$	-2.33	-1.96	-1.64	-1.28	1.28	1.64	1.96	2.33

$$(a) H_0 : y_t = y_{t-1} + \epsilon_t$$

$$H_1 : y_t = \phi_1 y_{t-1} + \epsilon_t \text{ for } \phi_1 < 1$$

$T$	0.010	0.025	0.050	0.100	0.900	0.950	0.975	0.990
25	-2.66	-2.26	-1.95	-1.60	0.92	1.33	1.70	2.16
50	-2.62	-2.25	-1.95	-1.61	0.91	1.31	1.66	2.08
100	-2.60	-2.24	-1.95	-1.61	0.90	1.29	1.64	2.03
250	-2.58	-2.23	-1.95	-1.62	0.89	1.29	1.63	2.01
500	-2.58	-2.23	-1.95	-1.62	0.89	1.28	1.62	2.00
$\infty$	-2.58	-2.23	-1.95	-1.62	0.89	1.28	1.62	2.00

To test  $H_0 : \rho = 0$  against  $H_1 : \rho < 0$ , estimate  $\Delta y_t = \rho y_{t-1} + \epsilon_t$  and compare the  $t$ -value of  $\rho$  with the above table.

$$(b) H_0 : y_t = y_{t-1} + \epsilon_t$$

$$H_1 : y_t = \alpha_0 + \phi_1 y_{t-1} + \epsilon_t \text{ for } \phi_1 < 1$$

$T$	0.010	0.025	0.050	0.100	0.900	0.950	0.975	0.990
25	-3.75	-3.33	-3.00	-2.63	-0.37	0.00	0.34	0.72
50	-3.58	-3.22	-2.93	-2.60	-0.40	-0.03	0.29	0.66
100	-3.51	-3.17	-2.89	-2.58	-0.42	-0.05	0.26	0.63
250	-3.46	-3.14	-2.88	-2.57	-0.42	-0.06	0.24	0.62
500	-3.44	-3.13	-2.87	-2.57	-0.43	-0.07	0.24	0.61
$\infty$	-3.43	-3.12	-2.86	-2.57	-0.44	-0.07	0.23	0.60

To test  $H_0 : \rho = 0$  against  $H_1 : \rho < 0$ , estimate  $\Delta y_t = \alpha_0 + \rho y_{t-1} + \epsilon_t$  and compare the  $t$ -value of  $\rho$  with the above table.

$$(c) H_0 : y_t = \alpha_0 + y_{t-1} + \epsilon_t$$

$$H_1 : y_t = \alpha_0 + \alpha_1 t + \phi_1 y_{t-1} + \epsilon_t \text{ for } \phi_1 < 1$$

$T$	0.010	0.025	0.050	0.100	0.900	0.950	0.975	0.990
25	-4.38	-3.95	-3.60	-3.24	-1.14	-0.80	-0.50	-0.15
50	-4.15	-3.80	-3.50	-3.18	-1.19	-0.87	-0.58	-0.24
100	-4.04	-3.73	-3.45	-3.15	-1.22	-0.90	-0.62	-0.28
250	-3.99	-3.69	-3.43	-3.13	-1.23	-0.92	-0.64	-0.31
500	-3.98	-3.68	-3.42	-3.13	-1.24	-0.93	-0.65	-0.32
$\infty$	-3.96	-3.66	-3.41	-3.12	-1.25	-0.94	-0.66	-0.33

To test  $H_0 : \rho = 0$  against  $H_1 : \rho < 0$ , estimate  $\Delta y_t = \alpha_0 + \alpha_1 t + \rho y_{t-1} + \epsilon_t$  and compare the  $t$ -value of  $\rho$  with the above table.

## 8.2 Unit Root (More Formally)

Consider  $y_t = y_{t-1} + \epsilon_t$  and  $y_0 = 0$ .

$$y_t = \epsilon_1 + \epsilon_2 + \cdots + \epsilon_t \sim N(0, t\sigma^2)$$

$$\frac{1}{\sqrt{T}}y_t = \frac{1}{\sqrt{T}}(\epsilon_1 + \epsilon_2 + \cdots + \epsilon_t) \sim N(0, \frac{t}{T}\sigma^2) \longrightarrow N(0, r\sigma^2)$$

where  $0 \leq r \leq 1$  and  $r = \frac{t}{T}$ .

Note that time interval  $(1, T)$  is transformed into  $(0, 1)$ , divided by  $T$ .

$$\frac{1}{\sqrt{T}\sigma}y_t = \frac{1}{\sqrt{T}\sigma}(\epsilon_1 + \epsilon_2 + \cdots + \epsilon_t) \sim N(0, \frac{t}{T}) \longrightarrow N(0, r) \equiv W(r)$$

As  $T$  ( $t$  at the same time) goes to infinity keeping  $r = \frac{t}{T}$ ,  $W(r)$  results in a continuous function of  $r$  where  $r$  takes any number between zero and one.

$W(r)$  is a normal random variable with mean zero and variance  $r$  and it is called the **Brownian motion**.

Moreover, we consider the following:

$$\frac{1}{\sqrt{T}\sigma}y_{t'} = \frac{1}{\sqrt{T}\sigma}(\epsilon_1 + \epsilon_2 + \cdots + \epsilon_{t'}) \longrightarrow N(0, r') \equiv W(r').$$

For  $t' > t$ , we have the following:

$$\begin{aligned}\frac{1}{\sqrt{T}\sigma}y_{t'} &= \frac{1}{\sqrt{T}\sigma}(\epsilon_1 + \cdots + \epsilon_t + \epsilon_{t+1} + \cdots + \epsilon_{t'}) \longrightarrow N(0, r') \equiv W(r') \\ &= \frac{1}{\sqrt{T}\sigma}y_t + \frac{1}{\sqrt{T}\sigma}(\epsilon_{t+1} + \cdots + \epsilon_{t'}).\end{aligned}$$

Therefore, we have

$$\frac{1}{\sqrt{T}\sigma}y_{t'} - \frac{1}{\sqrt{T}\sigma}y_t = \frac{1}{\sqrt{T}\sigma}(\epsilon_{t+1} + \cdots + \epsilon_{t'}) \longrightarrow N(0, r' - r) \equiv W(r') - W(r).$$

That is,  $W(r)$  is independent of  $W(r') - W(r)$  for  $r' > r$ .



Moreover, note as follows:

$$\frac{1}{T\sqrt{T}\sigma} \sum_{t=1}^T y_t = \frac{1}{T} \sum_{t=1}^T \left( \frac{y_t}{\sqrt{T}\sigma} \right) \longrightarrow \int_0^1 W(r) dr$$

where  $\frac{1}{T}$  and  $\sum_{t=1}^T$  are replaced by  $dr$  and  $\int_0^1$  as  $T$  goes to infinity.

We divide the time interval  $(0, 1)$  into  $T$  time intervals  $\left(\frac{t}{T}, \frac{t+1}{T}\right)$ .

That is, time interval  $(1, T)$  is transformed into  $(0, 1)$ .

(\*) We know that  $\frac{y_t}{\sqrt{T}\sigma} \longrightarrow W(r)$  as  $\frac{t}{T} \longrightarrow r$ .

**Summary: Properties of  $W(r)$  for  $0 < r < 1$ :**

1.  $W(r) \equiv N(0, r) \implies W(r)$  is a random variable.
2.  $W(1) \equiv N(0, 1)$
3.  $W(1)^2 \equiv \chi^2(1) \implies$  Remember that  $Z^2 \sim \chi^2(1)$  when  $Z \sim N(0, 1)$ .
4.  $W(r)$  is independent of  $W(r') - W(r)$  for  $r < r'$ .
5.  $W(r_4) - W(r_3)$  is independent of  $W(r_2) - W(r_1)$  for  $0 \leq r_1 < r_2 < r_3 < r_4 \leq 1$ .  
 $\implies$  The interval between  $r_4$  and  $r_3$  is not overlapped with the interval between  $r_2$  and  $r_1$ .

- **True Model**  $y_t = y_{t-1} + \epsilon_t$  vs **Estimated Model**  $y_t = \phi y_{t-1} + \epsilon_t$ : Under  $\phi = 1$ , we estimate  $\phi$  in the regression model:

$$y_t = \phi y_{t-1} + \epsilon_t$$

OLS of  $\phi$  is:

$$\hat{\phi} = \frac{\sum_{t=1}^T y_{t-1} y_t}{\sum_{t=1}^T y_{t-1}^2} = \phi + \frac{\sum_{t=1}^T y_{t-1} \epsilon_t}{\sum_{t=1}^T y_{t-1}^2}$$

As mentioned above, the numerator is related to:

$$\frac{1}{\sigma^2 T} \sum_{t=1}^T y_{t-1} \epsilon_t = \frac{1}{2} \left( \frac{y_T}{\sigma \sqrt{T}} \right)^2 - \frac{1}{2\sigma^2} \frac{1}{T} \sum_{t=1}^T \epsilon_t^2 \rightarrow \frac{1}{2} W(1)^2 - \frac{1}{2}$$

which is rewritten by using the Brownian motion  $W(1)$ .

The denominator is:

$$\frac{1}{\sigma^2 T^2} \sum_{t=1}^T y_{t-1}^2 \approx \frac{1}{\sigma^2 T^2} \sum_{t=1}^T y_t^2 = \frac{1}{T} \sum_{t=1}^T \left( \frac{y_t}{\sigma \sqrt{T}} \right)^2 \rightarrow \int_0^1 W(r)^2 dr$$

where  $\frac{1}{T} \rightarrow dr$  and  $\frac{y_t}{\sigma\sqrt{T}} \rightarrow W(r)$  for  $\frac{t}{T} \rightarrow r$ .

Thus, under  $\phi = 1$ ,  $T(\hat{\phi} - \phi)$  is asymptotically distributed as follows:

$$T(\hat{\phi} - \phi) = T(\hat{\phi} - 1) = \frac{\frac{1}{\sigma^2 T} \sum_{t=1}^T y_{t-1} \epsilon_t}{\frac{1}{\sigma^2 T^2} \sum_{t=1}^T y_{t-1}^2} \rightarrow \frac{\frac{1}{2}(W(1)^2 - 1)}{\int_0^1 W(r)^2 dr}$$

• *t* value:

In the regression model:  $y_t - y_{t-1} \equiv \Delta y_t = \rho y_{t-1} + \epsilon_t$ , OLSE of  $\rho = \phi - 1$  is given by  $\hat{\rho} = \hat{\phi} - 1$ .

*t* value is  $\frac{\hat{\rho}}{s_\rho} = \frac{\hat{\phi} - 1}{s_\phi}$ , where  $s_\rho$  and  $s_\phi$  denote the standard errors of  $\hat{\rho}$  and  $\hat{\phi}$ .

Note that  $s_\rho = s_\phi$  because of  $V(\hat{\rho}) = V(\hat{\phi} - 1) = V(\hat{\phi})$ .

The standard error of  $\hat{\phi}$ , denoted by  $s_\phi$ , is given by:  $s_\phi^2 = \frac{s^2}{\sum_{t=1}^T y_{t-1}^2}$ , where  $s^2 = \frac{1}{T} \sum_{t=1}^T (y_t - \hat{\phi} y_{t-1})^2$ , called the standard error of regression.

$T(\hat{\phi} - \phi) = T(\hat{\phi} - 1)$  converges in distribution.

$\hat{\phi}$  is a consistent estimator of  $\phi = 1$ , i.e.,  $\hat{\phi} \rightarrow \phi = 1$ .

Therefore,

$$s^2 = \frac{1}{T} \sum_{t=1}^T (y_t - \hat{\phi}y_{t-1})^2 \rightarrow E((y_t - \phi y_{t-1})^2) = E(\epsilon_t^2) = \sigma^2.$$

Moreover, as shown above,

$$\frac{1}{T^2\sigma^2} \sum_{t=1}^T y_t^2 \rightarrow \int_0^1 W(r)^2 dr$$

Therefore, from  $s_\phi^2 = \frac{1}{T^2\sigma^2} \frac{s^2}{\frac{1}{T} \sum_{t=1}^T y_{t-1}^2}$ , we obtain

$$T^2 s_\phi^2 = \frac{1}{\sigma^2} \frac{s^2}{\frac{1}{T} \sum_{t=1}^T y_{t-1}^2} \rightarrow \left( \int_0^1 W(r)^2 dr \right)^{-1}.$$

Therefore,  $t$  value is given by:

$$\frac{\hat{\phi} - 1}{s_{\phi}} = \frac{T(\hat{\phi} - 1)}{\sqrt{T^2 s_{\phi}^2}} \rightarrow \frac{\frac{1}{2}(W(1)^2 - 1)}{\int_0^1 W(r)^2 dr} = \frac{\frac{1}{2}(W(1)^2 - 1)}{\left(\int_0^1 W(r)^2 dr\right)^{1/2}},$$

which is not a normal distribution.