

4 Generalized Least Squares Method (GLS, 一般化最小自乘法)

1. Regression model: $y = X\beta + u$, $u \sim N(0, \sigma^2\Omega)$

2. **Heteroscedasticity** (不等分散, 不均一分散)

$$\sigma^2\Omega = \begin{pmatrix} \sigma_1^2 & 0 & \cdots & 0 \\ 0 & \sigma_2^2 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & \sigma_n^2 \end{pmatrix}$$

First-Order Autocorrelation (一階の自己相関, 系列相関)

In the case of time series data, the subscript is conventionally given by t , not i .

$$u_t = \rho u_{t-1} + \epsilon_t, \quad \epsilon_t \sim \text{iid } N(0, \sigma_\epsilon^2)$$

$$\sigma^2 \Omega = \frac{\sigma_\epsilon^2}{1 - \rho^2} \begin{pmatrix} 1 & \rho & \rho^2 & \cdots & \rho^{n-1} \\ \rho & 1 & \rho & \cdots & \rho^{n-2} \\ \rho^2 & \rho & 1 & \cdots & \rho^{n-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \rho^{n-1} & \rho^{n-2} & \rho^{n-3} & \cdots & 1 \end{pmatrix}$$

$$V(u_t) = \sigma^2 = \frac{\sigma_\epsilon^2}{1 - \rho^2}$$

3. The Generalized Least Squares (GLS, 一般化最小二乘法) estimator of β , denoted by b , solves the following minimization problem:

$$\min_b (y - Xb)' \Omega^{-1} (y - Xb)$$

The GLSE of β is:

$$b = (X'\Omega^{-1}X)^{-1}X'\Omega^{-1}y$$

4. In general, when Ω is symmetric, Ω is decomposed as follows.

$$\Omega = A'\Lambda A$$

Λ is a diagonal matrix, where the diagonal elements of Λ are given by the eigen values.

A is a matrix consisting of eigen vectors.

When Ω is a positive definite matrix, all the diagonal elements of Λ are positive.

5. There exists P such that $\Omega = PP'$ (i.e., take $P = A'\Lambda^{1/2}$). $\implies P^{-1}\Omega P'^{-1} = I_n$

Multiply P^{-1} on both sides of $y = X\beta + u$.

We have:

$$y^* = X^*\beta + u^*,$$

where $y^* = P^{-1}y$, $X^* = P^{-1}X$, and $u^* = P^{-1}u$.

The variance of u^* is:

$$V(u^*) = V(P^{-1}u) = P^{-1}V(u)P'^{-1} = \sigma^2 P^{-1}\Omega P'^{-1} = \sigma^2 I_n.$$

because $\Omega = PP'$, i.e., $P^{-1}\Omega P'^{-1} = I_n$.

Accordingly, the regression model is rewritten as:

$$y^* = X^*\beta + u^*, \quad u^* \sim (0, \sigma^2 I_n)$$

Apply OLS to the above model.

Let b be as estimator of β from the above model.

That is, the minimization problem is given by:

$$\min_b (y^* - X^*b)'(y^* - X^*b),$$

which is equivalent to:

$$\min_b (y - Xb)' \Omega^{-1} (y - Xb).$$

Solving the minimization problem above, we have the following estimator:

$$\begin{aligned} b &= (X^{*\prime} X^*)^{-1} X^{*\prime} y^* \\ &= (X' \Omega^{-1} X)^{-1} X' \Omega^{-1} y, \end{aligned}$$

which is called GLS (Generalized Least Squares) estimator.

b is rewritten as follows:

$$b = \beta + (X^{*\prime} X^*)^{-1} X^{*\prime} u^* = \beta + (X' \Omega^{-1} X)^{-1} X' \Omega^{-1} u$$

The mean and variance of b are given by:

$$E(b) = \beta,$$

$$V(b) = \sigma^2 (X^{*\prime} X^*)^{-1} = \sigma^2 (X' \Omega^{-1} X)^{-1}.$$

6. Suppose that the regression model is given by:

$$y = X\beta + u, \quad u \sim N(0, \sigma^2\Omega).$$

In this case, when we use OLS, what happens?

$$\hat{\beta} = (X'X)^{-1}X'y = \beta + (X'X)^{-1}X'u$$

$$V(\hat{\beta}) = \sigma^2(X'X)^{-1}X'\Omega X(X'X)^{-1}$$

Compare GLS and OLS.

(a) Expectation:

$$E(\hat{\beta}) = \beta, \quad \text{and} \quad E(b) = \beta$$

Thus, both $\hat{\beta}$ and b are unbiased estimator.

(b) Variance:

$$V(\hat{\beta}) = \sigma^2(X'X)^{-1}X'\Omega X(X'X)^{-1}$$

$$V(b) = \sigma^2(X'\Omega^{-1}X)^{-1}$$

Which is more efficient, OLS or GLS?.

$$\begin{aligned}
V(\hat{\beta}) - V(b) &= \sigma^2(X'X)^{-1}X'\Omega X(X'X)^{-1} - \sigma^2(X'\Omega^{-1}X)^{-1} \\
&= \sigma^2\left((X'X)^{-1}X' - (X'\Omega^{-1}X)^{-1}X'\Omega^{-1}\right)\Omega \\
&\quad \times\left((X'X)^{-1}X' - (X'\Omega^{-1}X)^{-1}X'\Omega^{-1}\right)' \\
&= \sigma^2A\Omega A'
\end{aligned}$$

Note that A is $k \times n$ and Ω is $n \times n$.

Ω is the variance-covariance matrix of u , which is a positive definite matrix.

Therefore, except for $\Omega = I_n$, $A\Omega A'$ is also a positive definite matrix.

(From $\Omega = PP'$ and $A\Omega A' = AP(AP)'$, we have $xAP(xAP)' = \sum_{i=1}^k z_i^2 > 0$ for $x \neq 0$, where x is $1 \times k$, $z = xAP$ is $1 \times k$ and $z = (z_1, z_2, \dots, z_k)$.)

This implies that $V(\hat{\beta}_i) - V(b_i) > 0$ for the i th element of β .

Accordingly, b is more efficient than $\hat{\beta}$.

7. If $u \sim N(0, \sigma^2\Omega)$, then $b \sim N(\beta, \sigma^2(X'\Omega^{-1}X)^{-1})$.