2 Some Formulas of Matrix Algebra

1. Let
$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1k} \\ a_{21} & a_{22} & \cdots & a_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ a_{l1} & a_{l2} & \cdots & a_{lk} \end{pmatrix} = [a_{ij}],$$

which is a $l \times k$ matrix, where a_{ij} denotes *i*th row and *j*th column of A.

The transposed matrix (転置行列) of A, denoted by A', is defined as:

$$A' = \begin{pmatrix} a_{11} & a_{21} & \cdots & a_{l1} \\ a_{12} & a_{22} & \cdots & a_{l2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1k} & a_{2k} & \cdots & a_{lk} \end{pmatrix} = [a_{ji}],$$

where the *i*th row of A' is the *i*th column of A.

2. (Ax)' = x'A',

where A and x are a $l \times k$ matrix and a $k \times 1$ vector, respectively.

3. a' = a,

where *a* denotes a scalar.

4.
$$\frac{\partial a'x}{\partial x} = a$$
,

where *a* and *x* are $k \times 1$ vectors.

5. If A is symmetric, A = A'.

6.
$$\frac{\partial x'Ax}{\partial x} = (A + A')x,$$

where A and x are a $k \times k$ matrix and a $k \times 1$ vector, respectively.

Especially, when A is symmetric,

$$\frac{\partial x'Ax}{\partial x} = 2Ax.$$

7. Let *A* and *B* be $k \times k$ matrices, and I_k be a $k \times k$ identity matrix (単位行列) (one in the diagonal elements and zero in the other elements).

When $AB = I_k$, *B* is called the **inverse matrix** (逆行列) of *A*, denoted by $B = A^{-1}$.

That is, $AA^{-1} = A^{-1}A = I_k$.

8. Let *A* be a $k \times k$ matrix and *x* be a $k \times 1$ vector.

If *A* is a **positive definite matrix** (正値定符号行列), for any *x* except for x = 0 we have:

If A is a positive semidefinite matrix (非負值定符号行列), for any x except

for x = 0 we have:

$x'Ax \ge 0.$

If *A* is a **negative definite matrix** (負値定符号行列), for any *x* except for x = 0 we have:

If *A* is a **negative semidefinite matrix** (非正値定符号行列), for any *x* except for x = 0 we have:

$$x'Ax \leq 0.$$

Trace, Rank and etc.: $A: k \times k$, $B: n \times k$, $C: k \times n$.

1. The trace
$$(\vdash \lor \neg \neg)$$
 of A is: tr(A) = $\sum_{i=1}^{k} a_{ii}$, where $A = [a_{ij}]$.

- 2. The **rank** (ランク, 階数) of *A* is the maximum number of linearly independent column (or row) vectors of *A*, which is denoted by rank(A).
- 3. If A is an **idempotent matrix** (べき等行列), $A = A^2$.
- 4. If *A* is an idempotent and symmetric matrix, $A = A^2 = A'A$.
- 5. *A* is idempotent if and only if the eigen values of *A* consist of 1 and 0.
- 6. If A is idempotent, rank(A) = tr(A).
- 7. tr(BC) = tr(CB)

Distributions in Matrix Form:

1. Let *X*, μ and Σ be $k \times 1$, $k \times 1$ and $k \times k$ matrices.

When $X \sim N(\mu, \Sigma)$, the density function of X is given by:

$$f(x) = \frac{1}{(2\pi)^{k/2} |\Sigma|^{1/2}} \exp\left(-\frac{1}{2}(x-\mu)' \Sigma^{-1}(x-\mu)\right).$$

 $E(X) = \mu$ and $V(X) = E((X - \mu)(X - \mu)') = \Sigma$

The moment-generating function: $\phi(\theta) = E\left(\exp(\theta'X)\right) = \exp(\theta'\mu + \frac{1}{2}\theta'\Sigma\theta)$

(*) In the univariate case, when $X \sim N(\mu, \sigma^2)$, the density function of X is:

$$f(x) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp\left(-\frac{1}{2\sigma^2}(x-\mu)^2\right).$$

2. If $X \sim N(\mu, \Sigma)$, then $(X - \mu)' \Sigma^{-1} (X - \mu) \sim \chi^2(k)$.

Note that $X'X \sim \chi^2(k)$ when $X \sim N(0, I_k)$.

3. X: $n \times 1$, Y: $m \times 1$, X ~ $N(\mu_x, \Sigma_x)$, Y ~ $N(\mu_y, \Sigma_y)$

X is independent of Y, i.e., $E((X - \mu_x)(Y - \mu_y)') = 0$ in the case of normal random variables.

$$\frac{(X - \mu_x)' \Sigma_x^{-1} (X - \mu_x)/n}{(Y - \mu_y)' \Sigma_y^{-1} (Y - \mu_y)/m} \sim F(n, m)$$

4. If $X \sim N(0, \sigma^2 I_n)$ and *A* is a symmetric idempotent $n \times n$ matrix of rank *G*, then $X'AX/\sigma^2 \sim \chi^2(G)$.

Note that X'AX = (AX)'(AX) and rank(A) = tr(A) because A is idempotent.

5. If $X \sim N(0, \sigma^2 I_n)$, *A* and *B* are symmetric idempotent $n \times n$ matrices of rank *G* and *K*, and AB = 0, then

$$\frac{X'AX}{G\sigma^2} \Big| \frac{X'BX}{K\sigma^2} = \frac{X'AX/G}{X'BX/K} \sim F(G, K).$$

3 Multiple Regression Model (重回帰モデル)

Up to now, only one independent variable, i.e., x_i , is taken into the regression model. We extend it to more independent variables, which is called the **multiple regression model** (重回帰モデル).

We consider the following regression model:

$$y_{i} = \beta_{1}x_{i,1} + \beta_{2}x_{i,2} + \dots + \beta_{k}x_{i,k} + u_{i} = (x_{i,1}, x_{i,2}, \dots, x_{i,k}) \begin{pmatrix} \beta_{1} \\ \beta_{2} \\ \vdots \\ \beta_{k} \end{pmatrix} + u_{i} = x_{i}\beta + u_{i},$$

for $i = 1, 2, \dots, n$, where x_i and β denote a $1 \times k$ vector of the independent variables

and a $k \times 1$ vector of the unknown parameters to be estimated, which are given by:

$$x_i = (x_{i,1}, x_{i,2}, \cdots, x_{i,k}), \qquad \beta = \begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{pmatrix}.$$

 $x_{i,j}$ denotes the *i*th observation of the *j*th independent variable. The case of k = 2 and $x_{i,1} = 1$ for all *i* is exactly equivalent to (1). Therefore, the matrix form above is a generalization of (1). Writing all the equations for $i = 1, 2, \dots, n$, we have:

$$y_{1} = \beta_{1}x_{1,1} + \beta_{2}x_{1,2} + \dots + \beta_{k}x_{1,k} + u_{1} = x_{1}\beta + u_{1},$$

$$y_{2} = \beta_{1}x_{2,1} + \beta_{2}x_{2,2} + \dots + \beta_{k}x_{2,k} + u_{2} = x_{2}\beta + u_{2},$$

$$\vdots$$

$$y_{n} = \beta_{1}x_{n,1} + \beta_{2}x_{n,2} + \dots + \beta_{k}x_{n,k} + u_{n} = x_{n}\beta + u_{n},$$

which is rewritten as:

$$\begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} x_{1,1} & x_{1,2} & \cdots & x_{1,k} \\ x_{2,1} & x_{2,2} & \cdots & x_{2,k} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n,1} & x_{n,2} & \cdots & x_{n,k} \end{pmatrix} \begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{pmatrix} + \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix}$$
$$= \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \beta + \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix}.$$

Again, the above equation is compactly rewritten as:

$$y = X\beta + u, \tag{18}$$

where *y*, *X* and *u* are denoted by:

$$y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}, \qquad X = \begin{pmatrix} x_{1,1} & x_{1,2} & \cdots & x_{1,k} \\ x_{2,1} & x_{2,2} & \cdots & x_{2,k} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n,1} & x_{n,2} & \cdots & x_{n,k} \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}, \qquad u = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix}$$

Utilizing the matrix form (18), we derive the ordinary least squares estimator of β , denoted by $\hat{\beta}$.

In (18), replacing β by $\hat{\beta}$, we have the following equation:

$$y = X\hat{\beta} + e,$$

where *e* denotes a $n \times 1$ vector of the residuals.

The *i*th element of *e* is given by e_i .

The sum of squared residuals is written as follows:

$$S(\hat{\beta}) = \sum_{i=1}^{n} e_i^2 = e'e = (y - X\hat{\beta})'(y - X\hat{\beta}) = (y' - \hat{\beta}'X')(y - X\hat{\beta})$$
$$= y'y - y'X\hat{\beta} - \hat{\beta}'X'y + \hat{\beta}'X'X\hat{\beta} = y'y - 2y'X\hat{\beta} + \hat{\beta}'X'X\hat{\beta}.$$

In the last equality, note that $\hat{\beta}' X' y = y' X \hat{\beta}$ because both are scalars.

To minimize $S(\hat{\beta})$ with respect to $\hat{\beta}$, we set the first derivative of $S(\hat{\beta})$ equal to zero, i.e.,

$$\frac{\partial S\left(\hat{\beta}\right)}{\partial\hat{\beta}} = -2X'y + 2X'X\hat{\beta} = 0.$$

Solving the equation above with respect to $\hat{\beta}$, the **ordinary least squares estimator** (**OLS**, 最小自乗推定量) of β is given by:

$$\hat{\beta} = (X'X)^{-1}X'y.$$
 (19)

Thus, the ordinary least squares estimator is derived in the matrix form.

(*) Remark

The second order condition for minimization:

$$\frac{\partial^2 S\left(\hat{\beta}\right)}{\partial \hat{\beta} \partial \hat{\beta}'} = 2X'X$$

is a positive definite matrix.

Set c = Xd.

For any $d \neq 0$, we have c'c = d'X'Xd > 0.

Now, in order to obtain the properties of $\hat{\beta}$ such as mean, variance, distribution and so on, (19) is rewritten as follows:

$$\hat{\beta} = (X'X)^{-1}X'y = (X'X)^{-1}X'(X\beta + u) = (X'X)^{-1}X'X\beta + (X'X)^{-1}X'u$$
$$= \beta + (X'X)^{-1}X'u.$$
(20)

Taking the expectation on both sides of (20), we have the following:

$$E(\hat{\beta}) = E(\beta + (X'X)^{-1}X'u) = \beta + (X'X)^{-1}X'E(u) = \beta,$$

because of E(u) = 0 by the assumption of the error term u_i .

Thus, unbiasedness of $\hat{\beta}$ is shown.

The variance of $\hat{\beta}$ is obtained as:

$$V(\hat{\beta}) = E((\hat{\beta} - \beta)(\hat{\beta} - \beta)') = E((X'X)^{-1}X'u((X'X)^{-1}X'u)')$$

= $E((X'X)^{-1}X'uu'X(X'X)^{-1}) = (X'X)^{-1}X'E(uu')X(X'X)^{-1}$
= $\sigma^2(X'X)^{-1}X'X(X'X)^{-1} = \sigma^2(X'X)^{-1}.$

The first equality is the definition of variance in the case of vector.

In the fifth equality, $E(uu') = \sigma^2 I_n$ is used, which implies that $E(u_i^2) = \sigma^2$ for all *i* and $E(u_i u_j) = 0$ for $i \neq j$.

Remember that u_1, u_2, \dots, u_n are assumed to be mutually independently and identically distributed with mean zero and variance σ^2 .